

results with complete & permanent tests on  
**128 Spark BPM electronics for ESRF's new L-E Ring**  
on real RF-beam signals

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Diag. group

ESRF



*Libera workshop 2018*

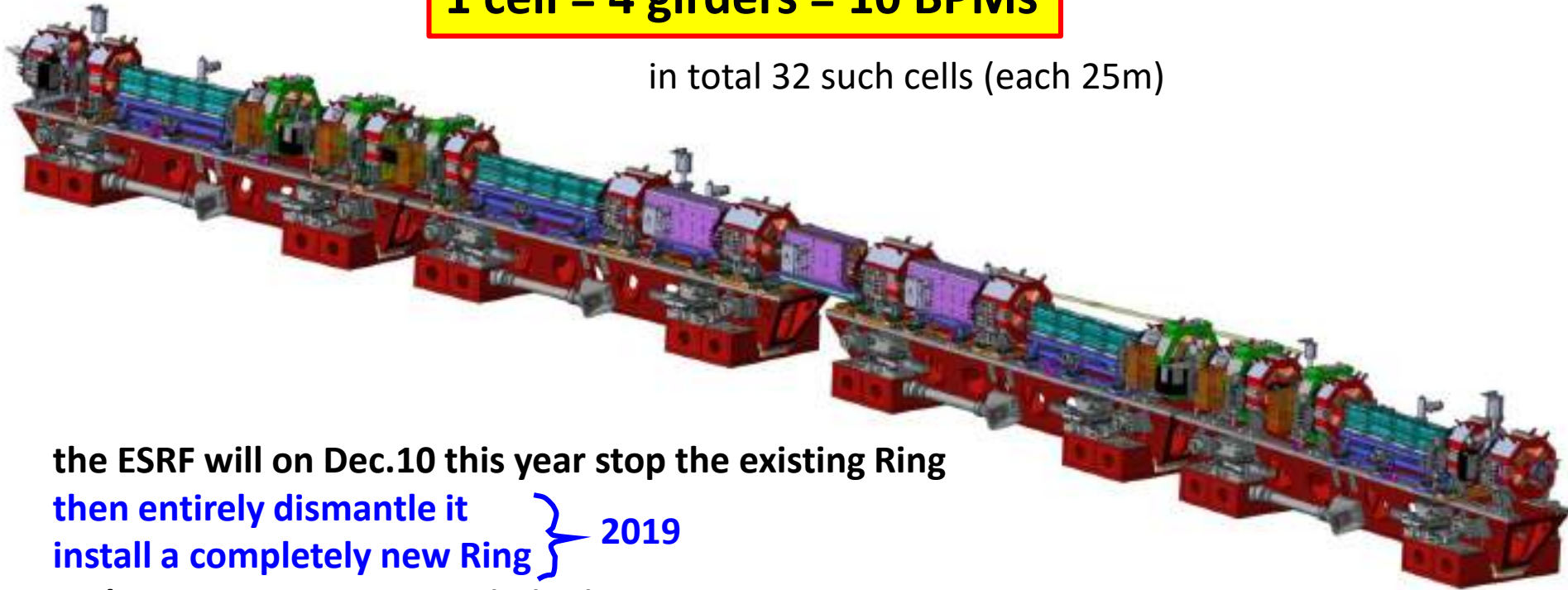
# **results with complete & permanent tests on 128 Spark BPM electronics for ESRF's new L-E Ring on real RF-beam signals**

## **Outline :**

- 1) Rapid recall of the situation of ESRF's new Storage Ring**
- 2) Configuration of the BPM-system, now (224 Liberas) and later : 192 Liberas + 128 Sparks**
- 3) Hybrid-system (Liberia / Spark) : → different functionalities & requirements**
- 4) Test set-up of the Sparks → permanent & simultaneous & parallel**
- 5) Results :**
  - slow, long-time records of :    stability, drift  
   reproducibility, reliability**
  - Turn-by-Turn measurement :    synchronization aspects**

**1 cell = 4 girders = 10 BPMs**

in total 32 such cells (each 25m)



the ESRF will on Dec.10 this year stop the existing Ring

then entirely dismantle it  
install a completely new Ring } 2019

and expects to start commissioning Jan. 2020

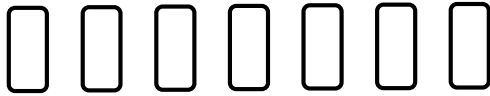
of relevance for this talk :      the number of BPMs will increase for 7 to 10 per cell,  
i.e. from 224 to 320 BPMs

this new Ring is also called :

Low-Emittance Ring (LE-Ring) or EBS (Extremely Brilliant Source)

## OLD Ring

7 BPMs



BPM-block

## NEW Ring

10 BPMs



electronics



total: 224 BPMs  
all doing Slow & Fast  
orbit correction

total: 320 BPMs

128 Sparks for Slow  
192 Liberas for Fast & Slow  
orbit correction

32 Liberas recup  
for extra spares \*

145 Sparks procured  
this Spring

subject of this talk

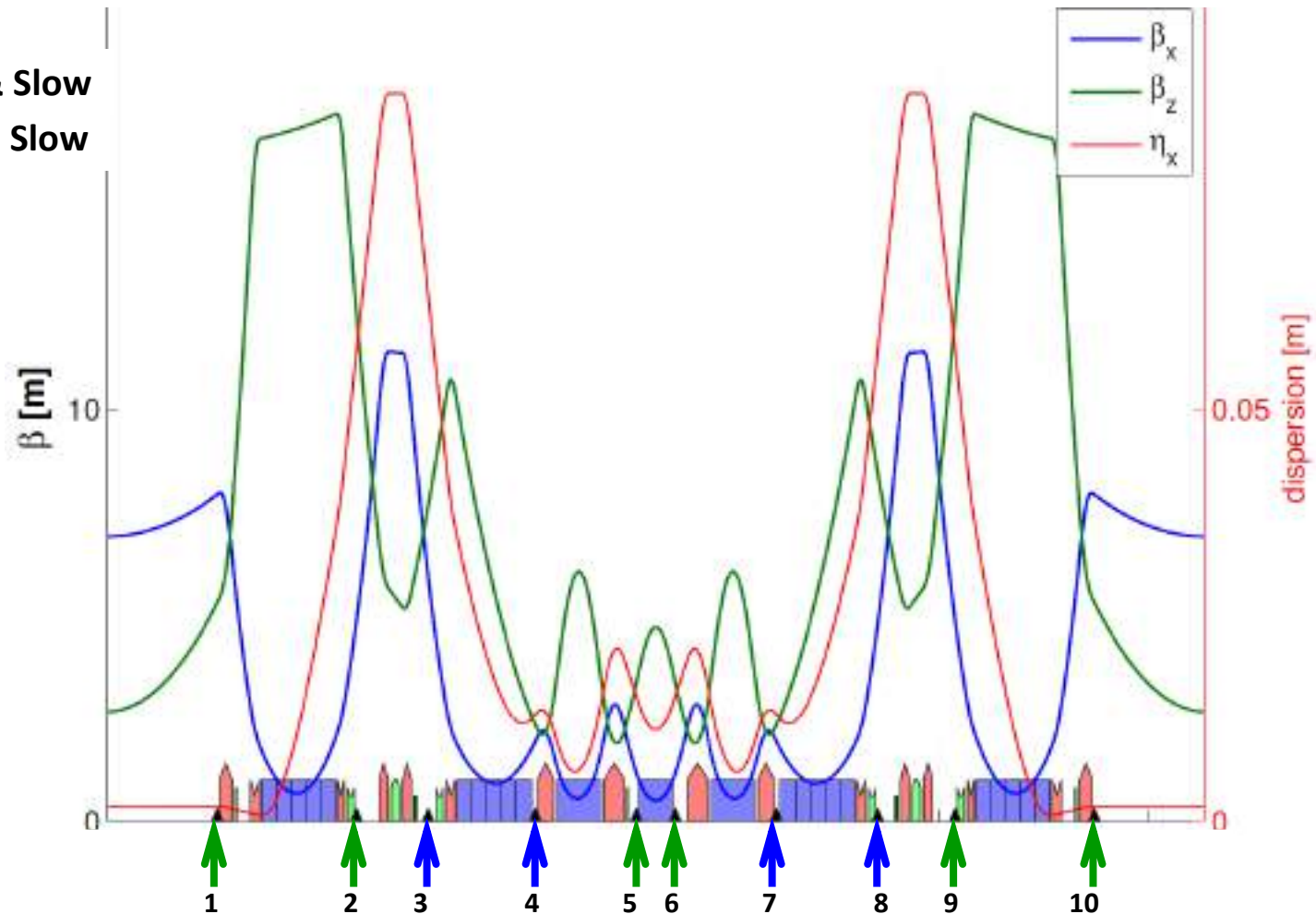
\* helpful : our Liberas are  
10 years old and obsolete

Fast & slow Orbit correction : 6 Liberas & 4 sparks per cell

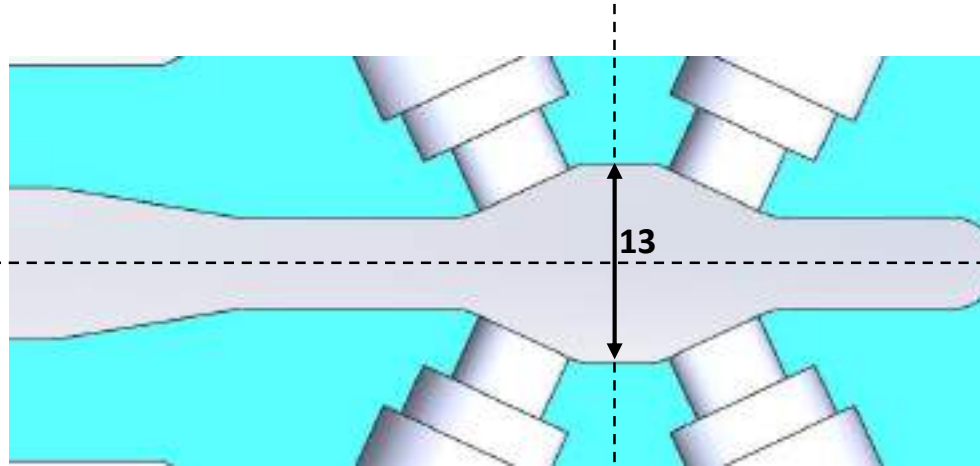
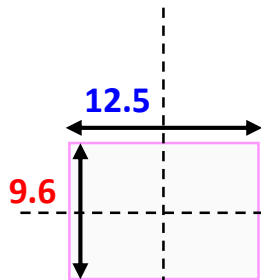
X-ray beam stability for users will be identical to that of today

6 Liberas : Fast & Slow  
4 Sparks : only Slow

↑ Libera  
↑ Spark



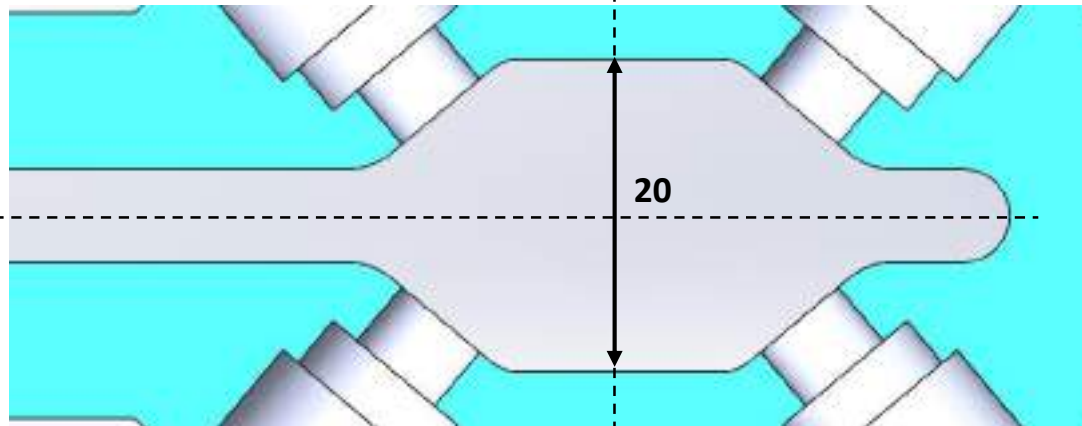
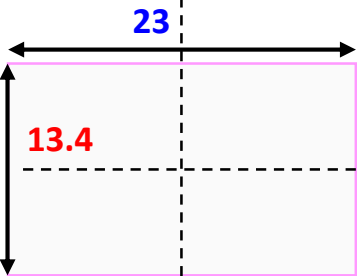
Beam-pipe much smaller than with old ring,  
also 2 different geometries : Large & Small



$K_x = 4.7$   
 $K_z = 7.4$

**BPM no.**  
**4 5 6 7**

**H & V** distances between  
the center of the 4 buttons



$K_x = 6.5$   
 $K_z = 16.4 \dots$

**BPM no.**  
**1 2 3      8 9 10**

## how to test 145 SPARK units ?

**FATs** done at each individual unit by the company (Jan. – April 2018)

followed by :

**SATs** done at ESRF, in the same manner as **FATs** .... ?? **NO !!**

a much **better alternatif** for **SATs** :

install them on real BPM signals, measuring X, Y, Sum

4 units (per cell) strictly in parallel, seeing identical beam motion

repeat for all 32 cells → test 128 in parallel & simultaneously & permanently

store the A-B-C-D data (SA) at 1Hz in data-base

**more info &  
checks on  
behavior &  
reliability**

install in same cubicles where they remain for operation in 2020

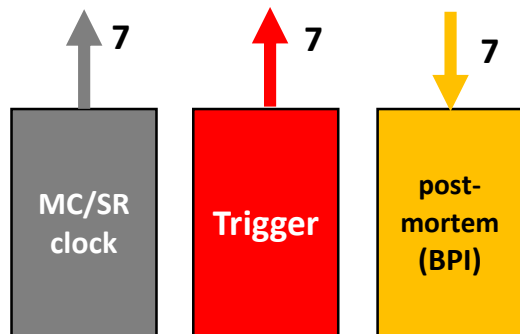
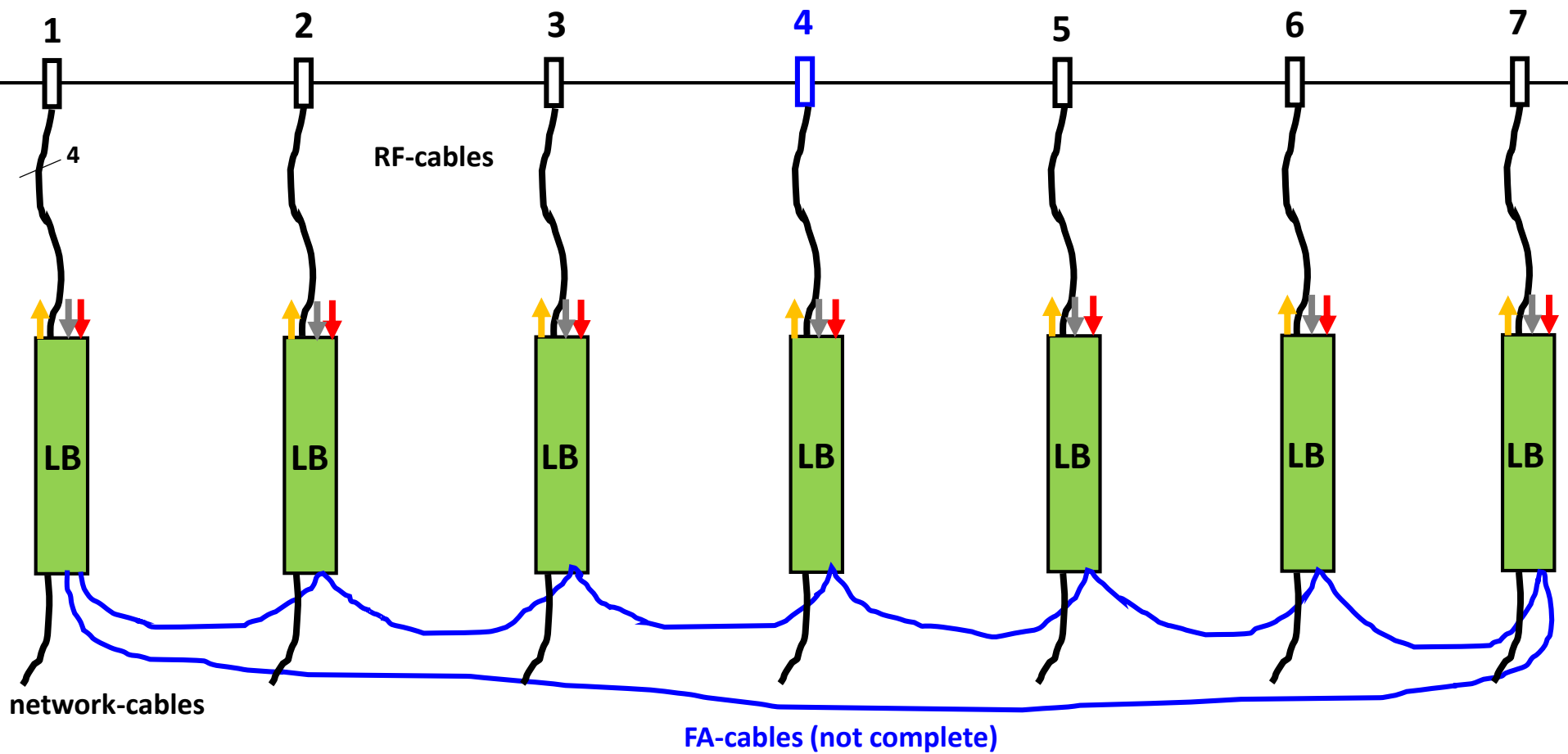
install & use the timings signals & network connections, as for 2020

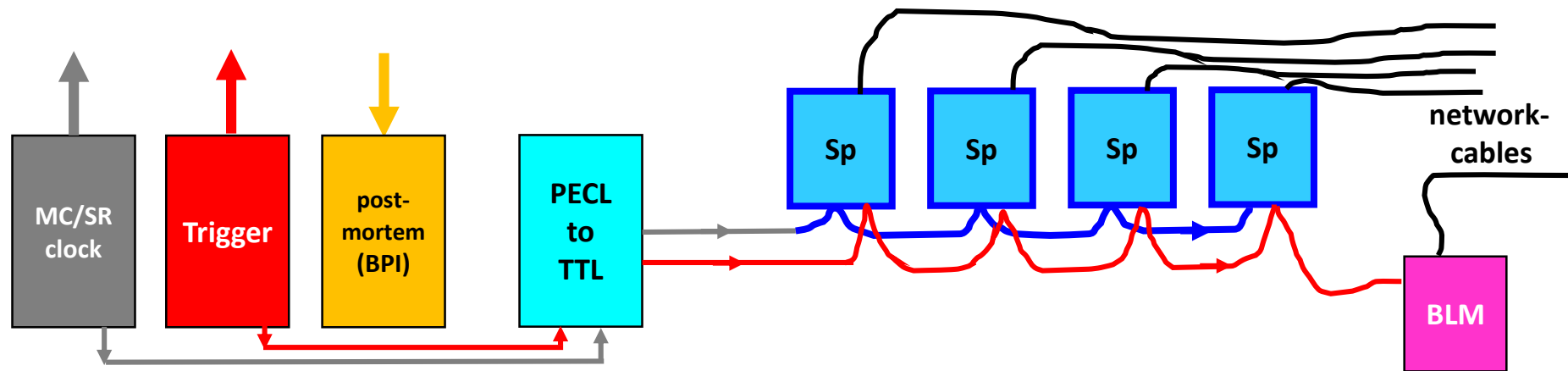
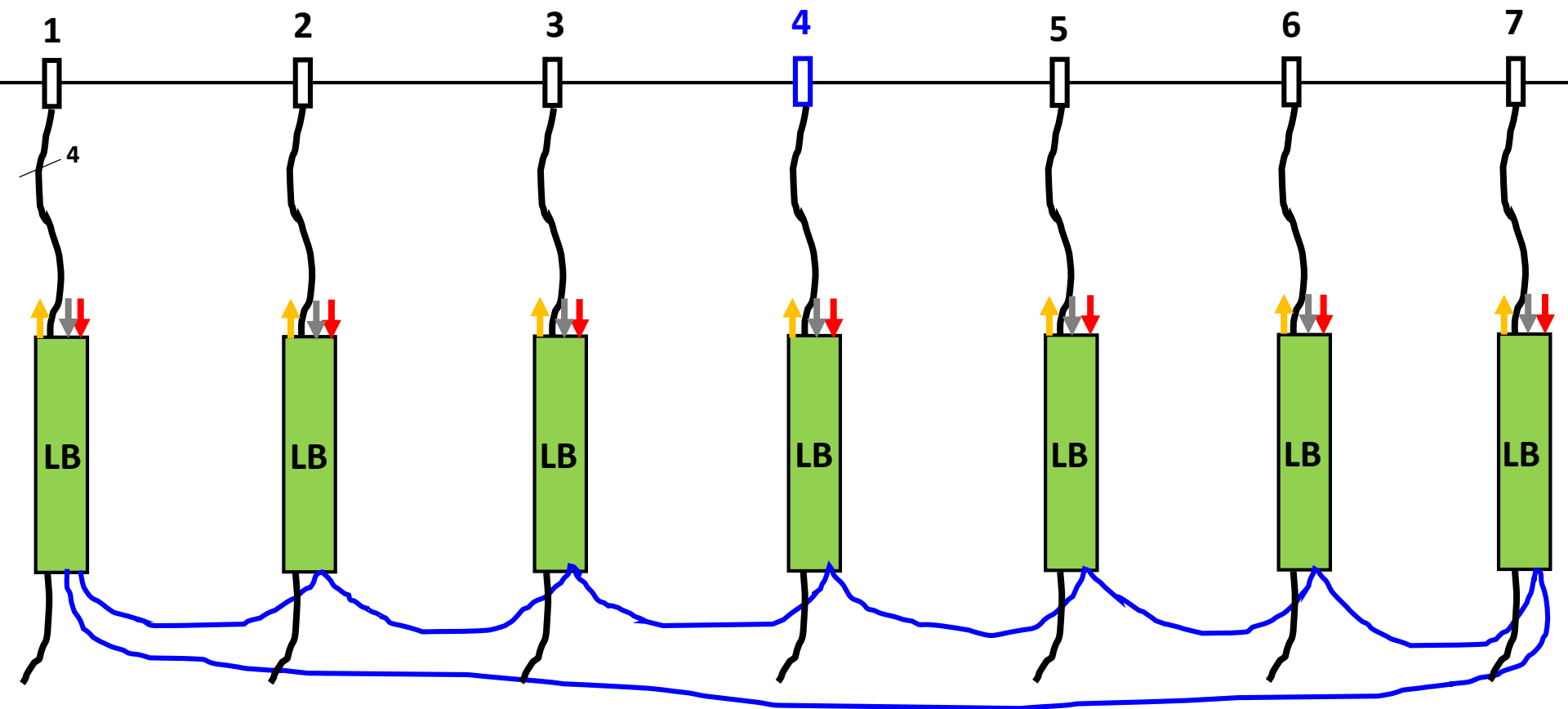
permanent test of software reliability & communication aspects

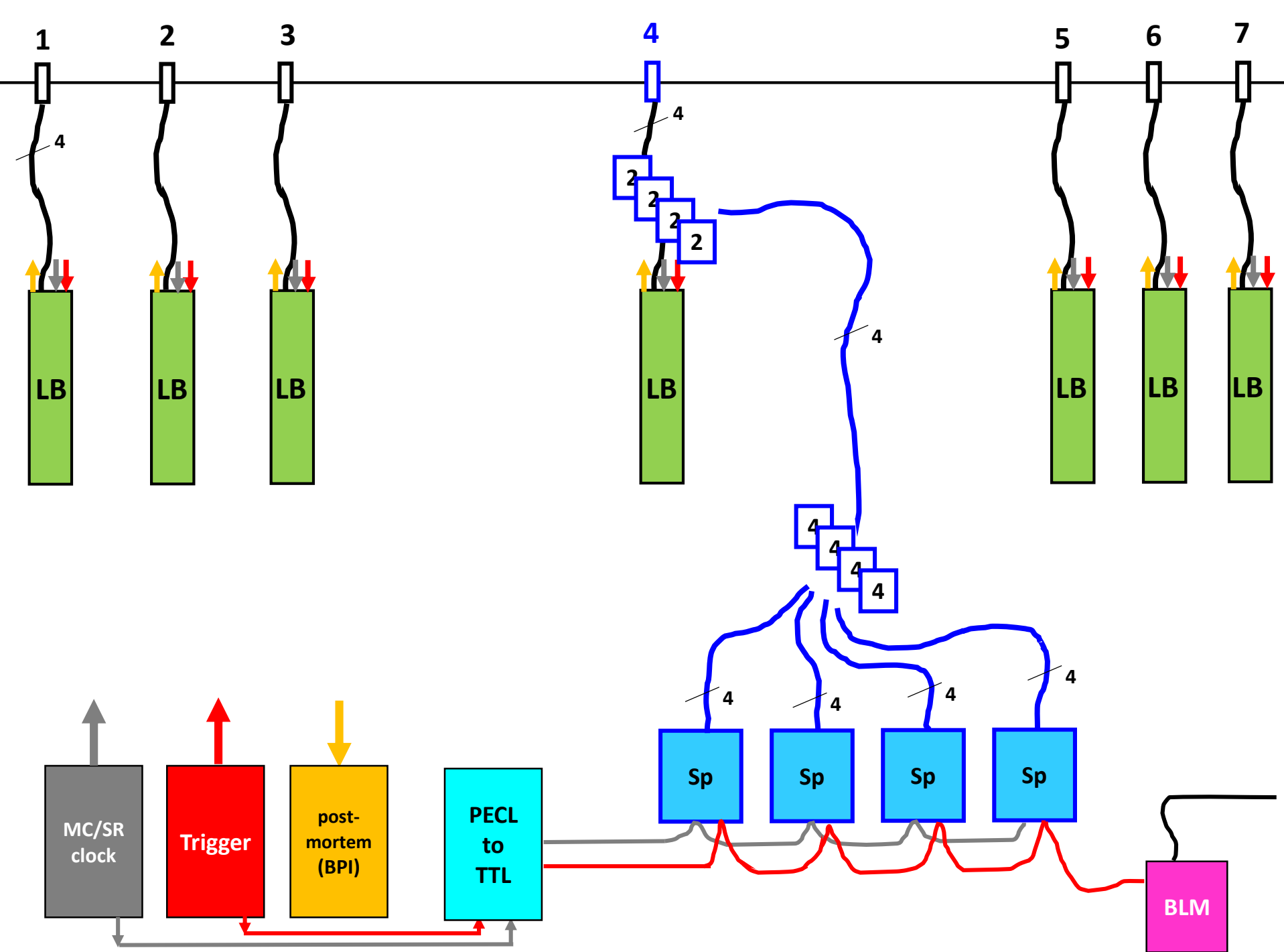
develop and test the higher level applications

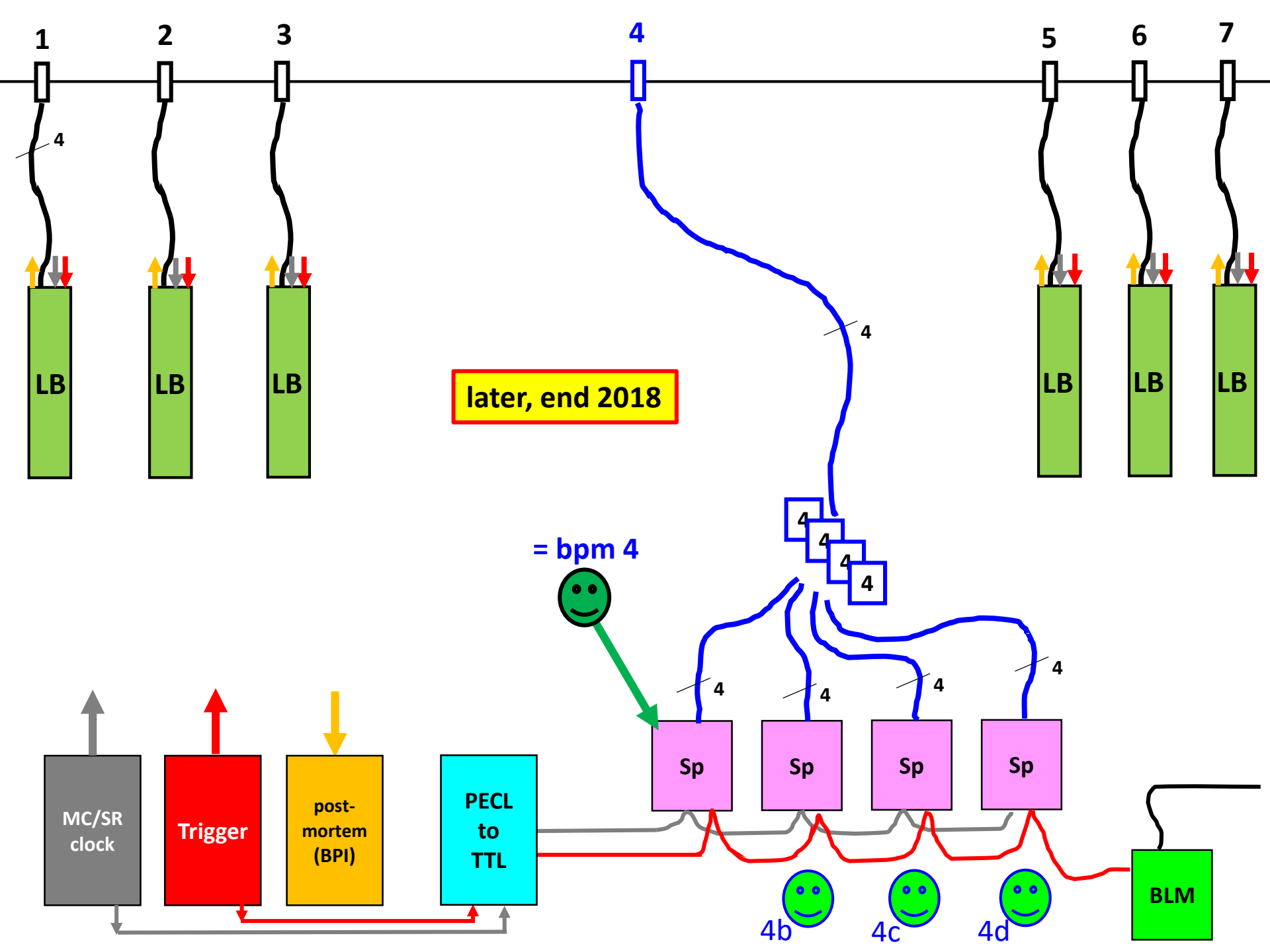
**job done in 2018 !!  
impossible in 2019  
difficult in 2020**

BPM blocks









network-switch

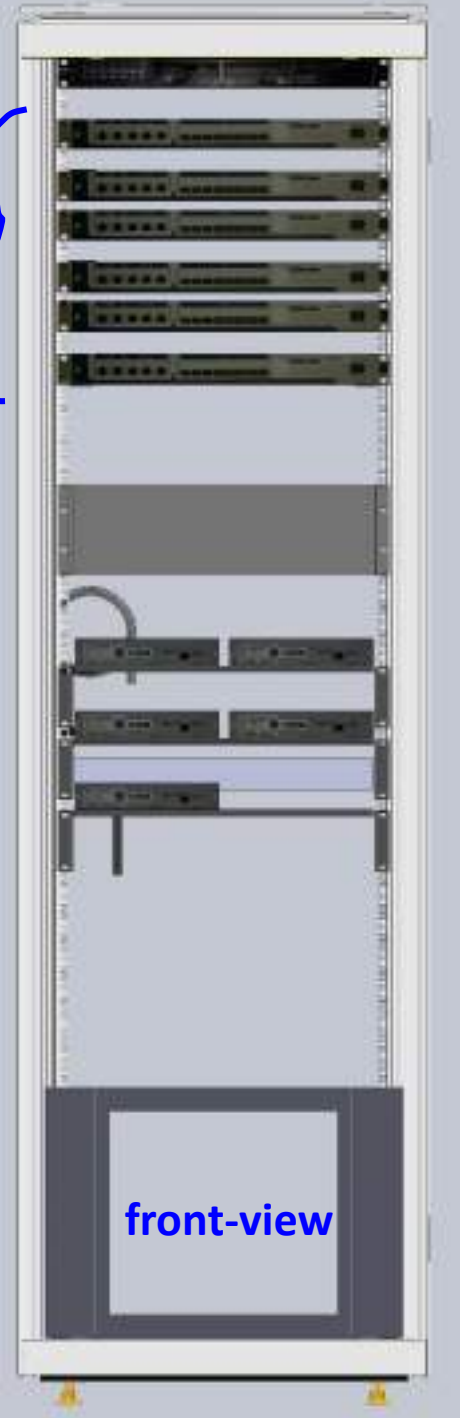
Liberas

timing-rack

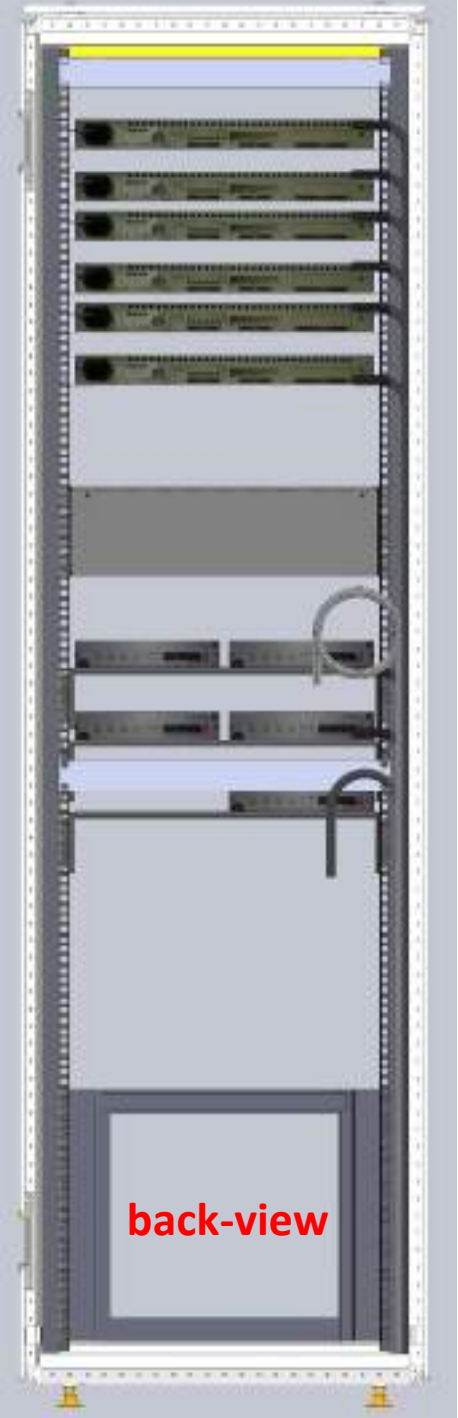
4 Sparks

1 BLM

front-view

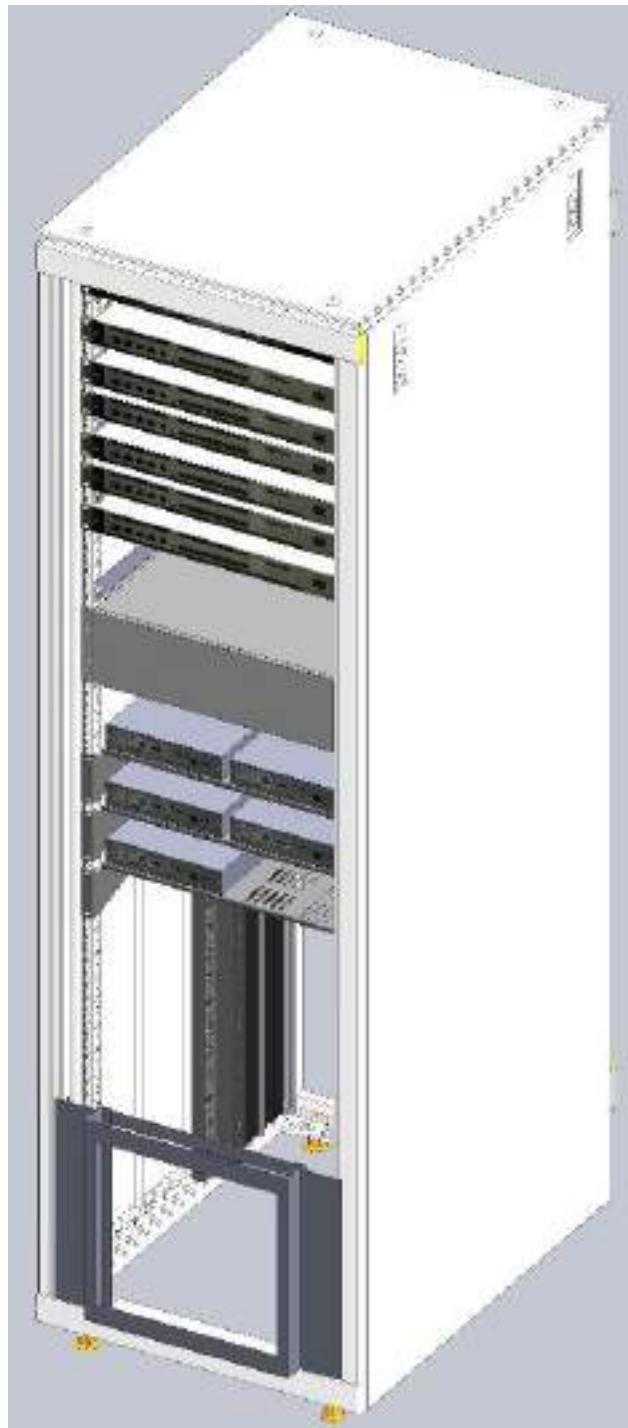
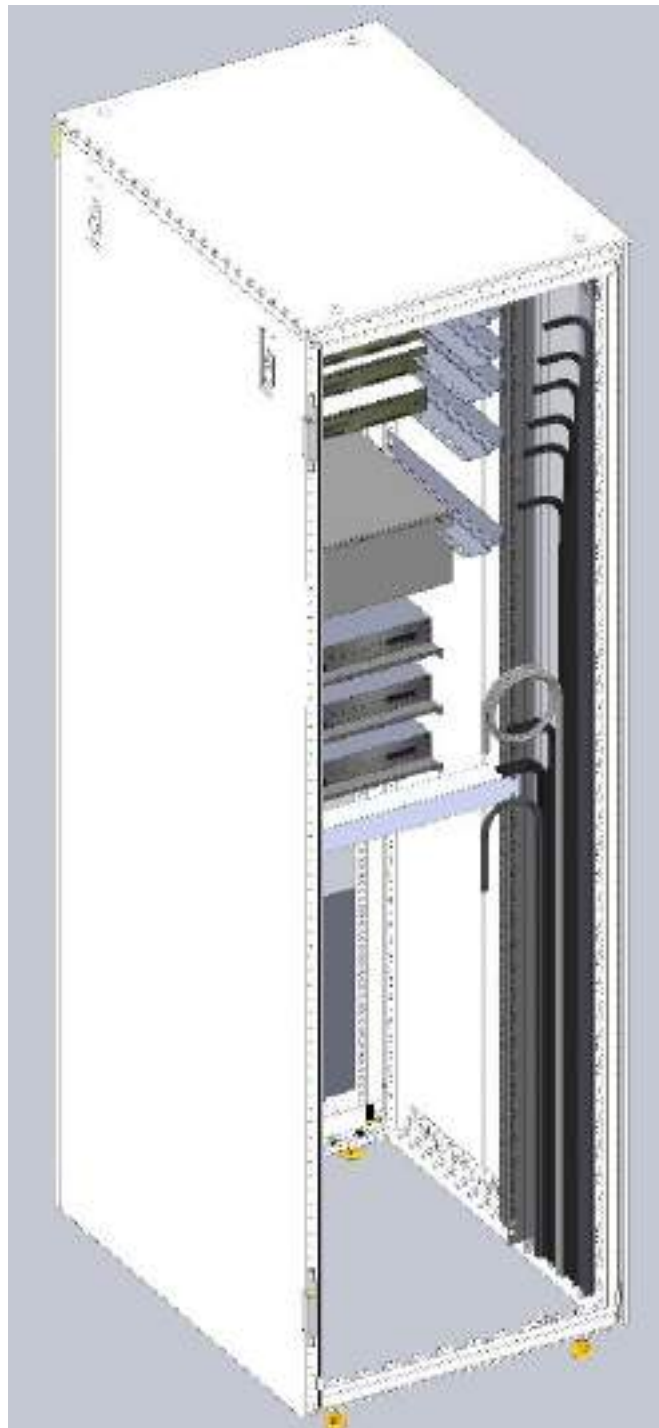


back-view

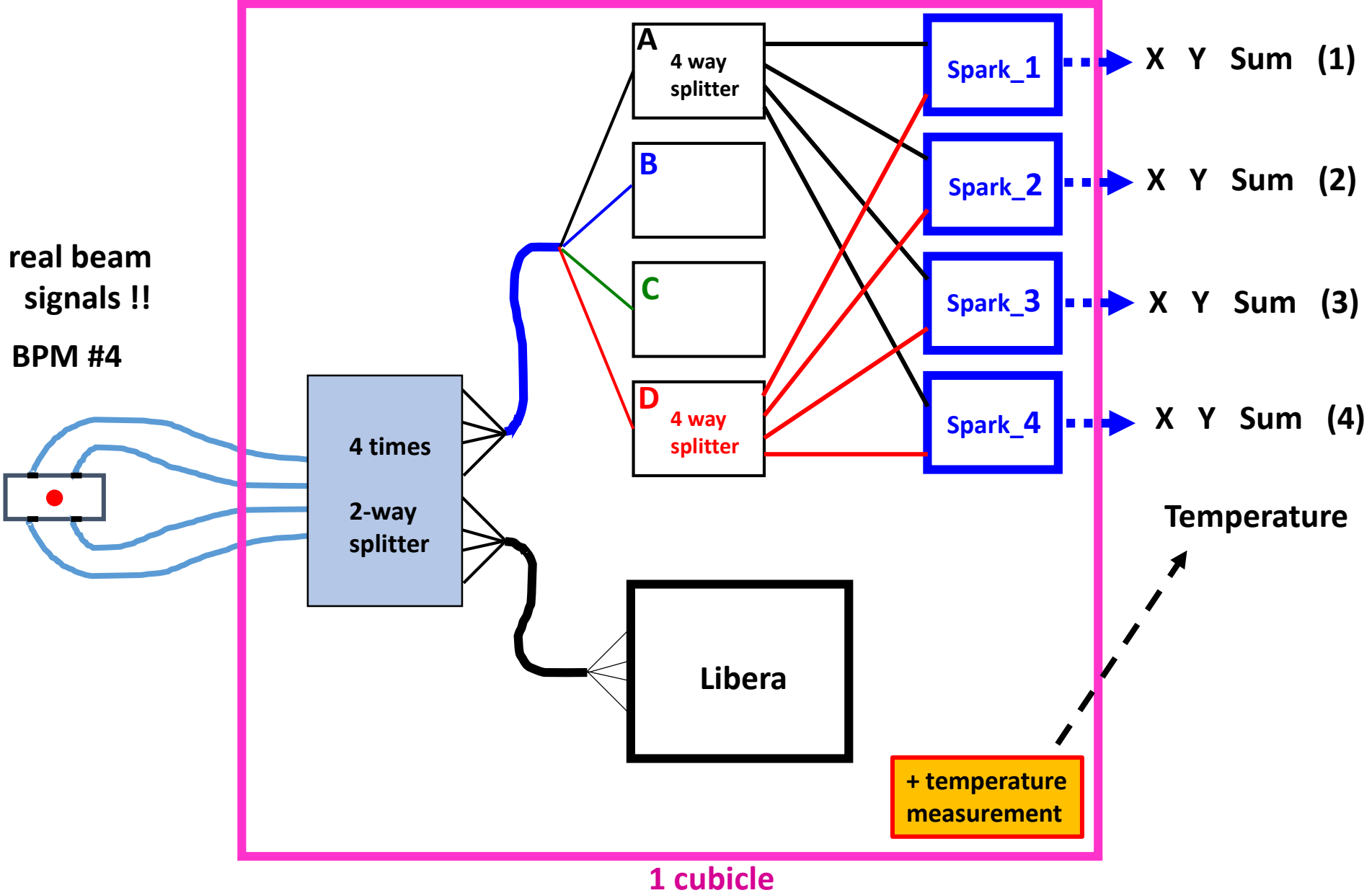


Cubicle with :

Liberas	7 later 6
Sparks	4
BLM	1



real beam  
signals !!  
BPM #4

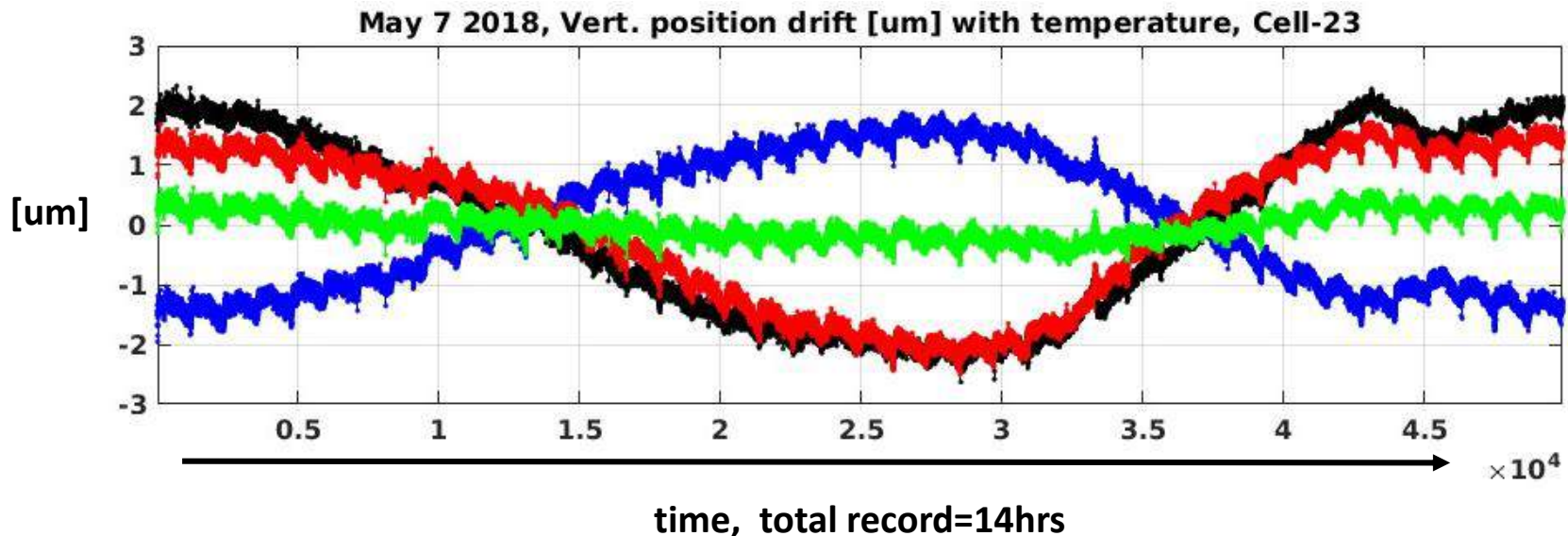


today's state (May 2018) :  
22 cells operational = 88 Sparks  
so still 10 cells more to do

analysis of SA-data (40Hz)  
stored at 1Hz rate  
in our database,  
pulled-out & scrutinized by  
specific routines & scripts

results and observations :

- stability with temperature
- stability over time (long-term drift, typ. 10-24hrs)
- short-time stability (typ. a few minutes)
- features / aberrations
- global reliability

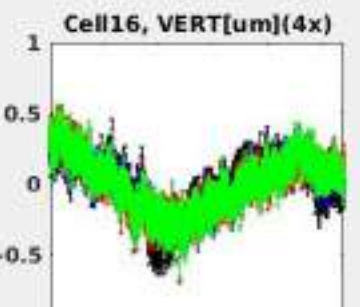
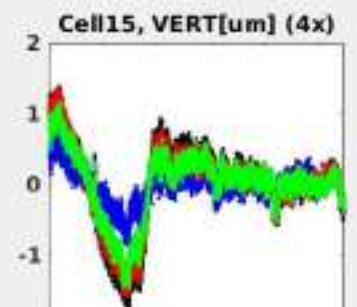
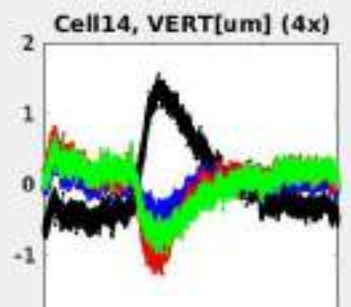
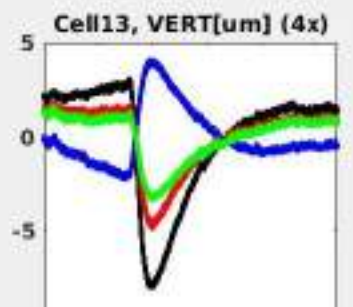
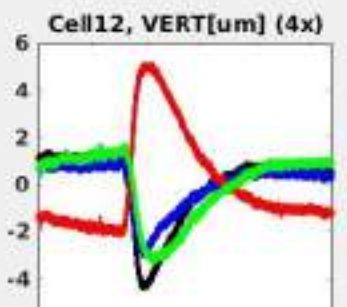
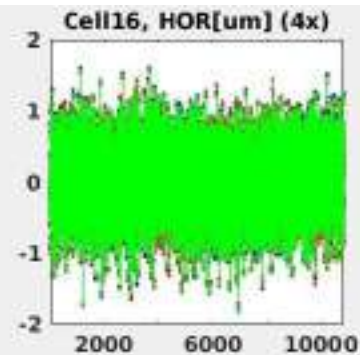
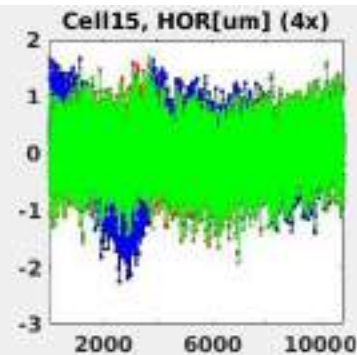
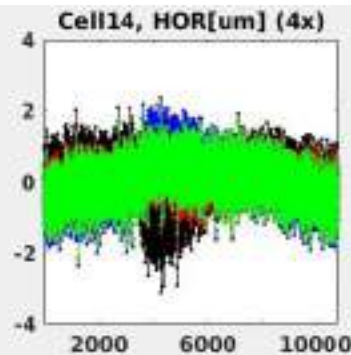
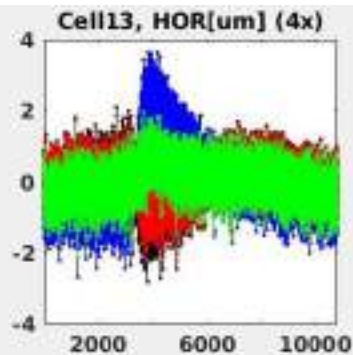
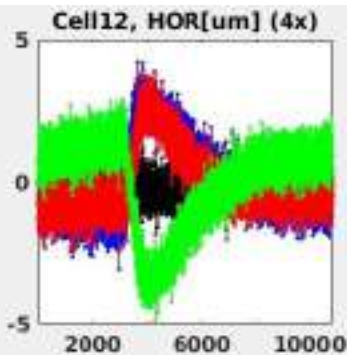


$T_{pk-pk} = 2.6\text{ C}$

$T_{pk-pk} = 1.2\text{ C}$

$T_{pk-pk} = 1.0\text{ C}$

$T_{pk-pk} = 0.6\text{ C}$

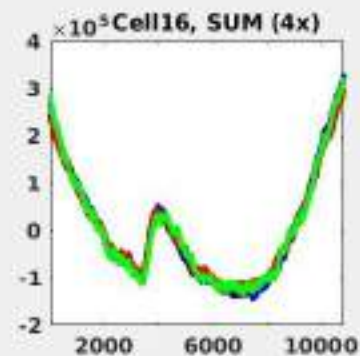
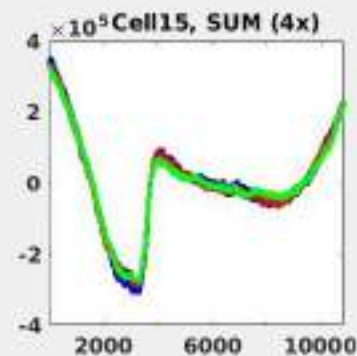
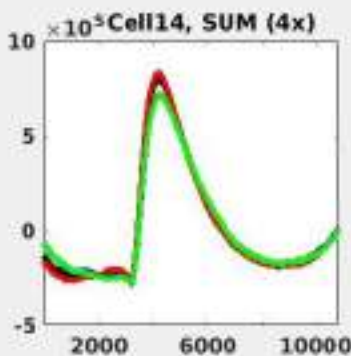
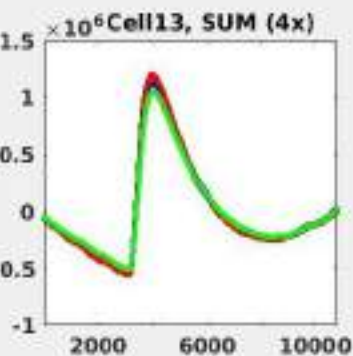
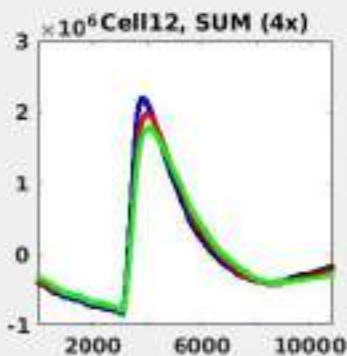


$Z_{pk-pk} = 7.3, 5.2, 4.8, 4.1\mu m$

$Z_{pk-pk} = 11, 6.6, 6.5, 4.7\mu m$

$Z_{pk-pk} = 2.0, 1.2, 1.1, 0.5\mu m$

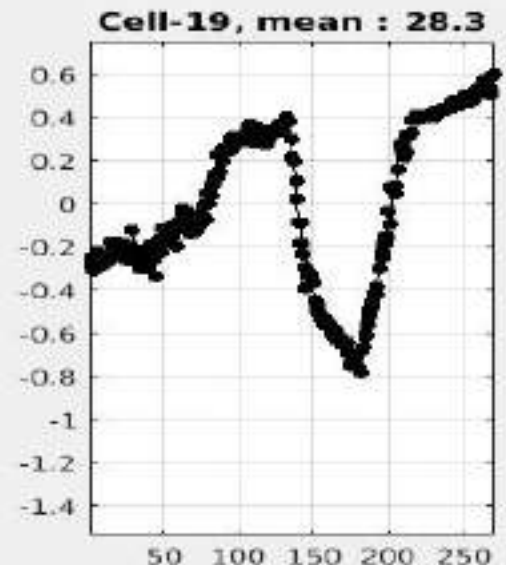
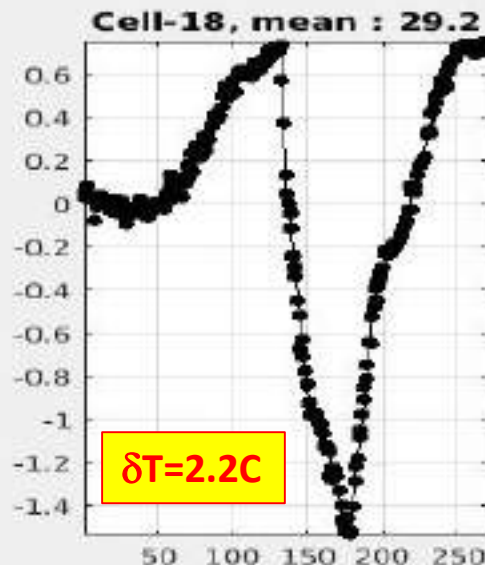
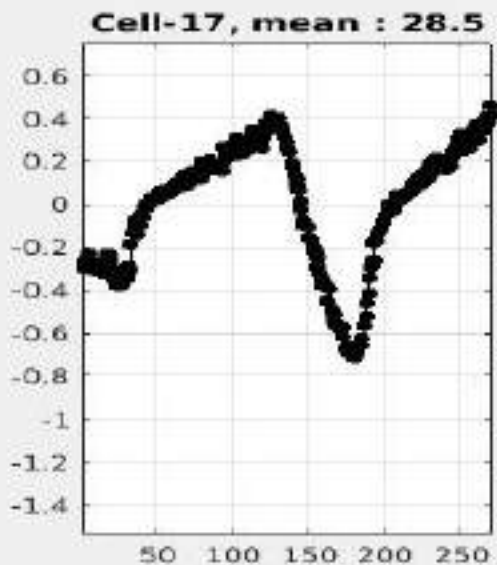
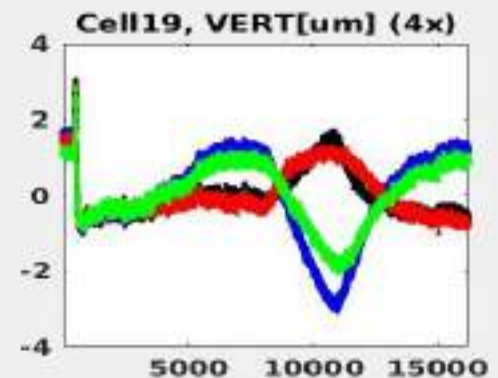
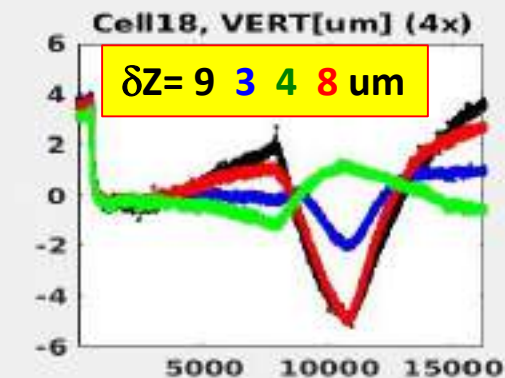
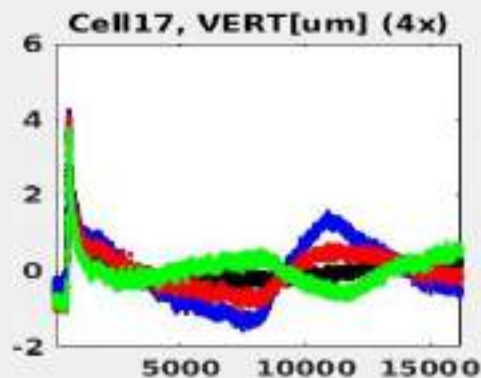
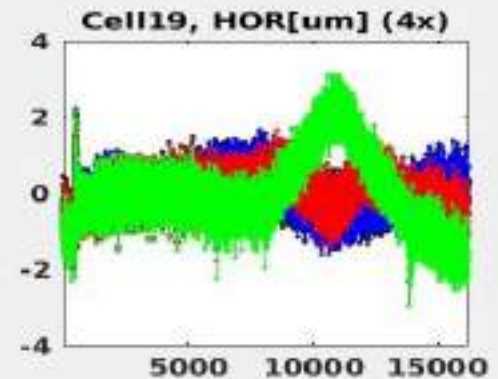
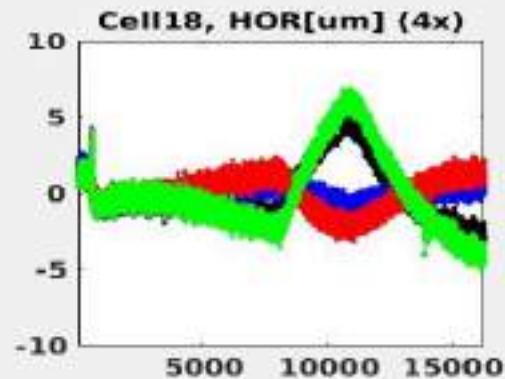
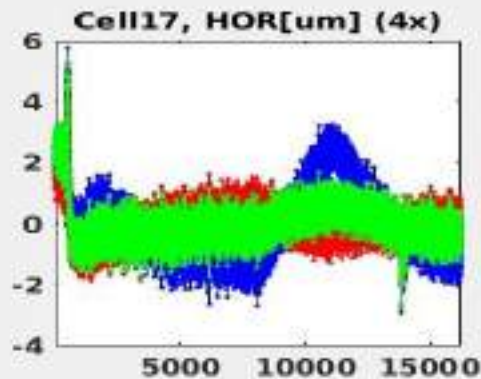
$Z_{pk-pk} = 2.9, 2.8, 2.0, 1.1\mu m$



3hrs

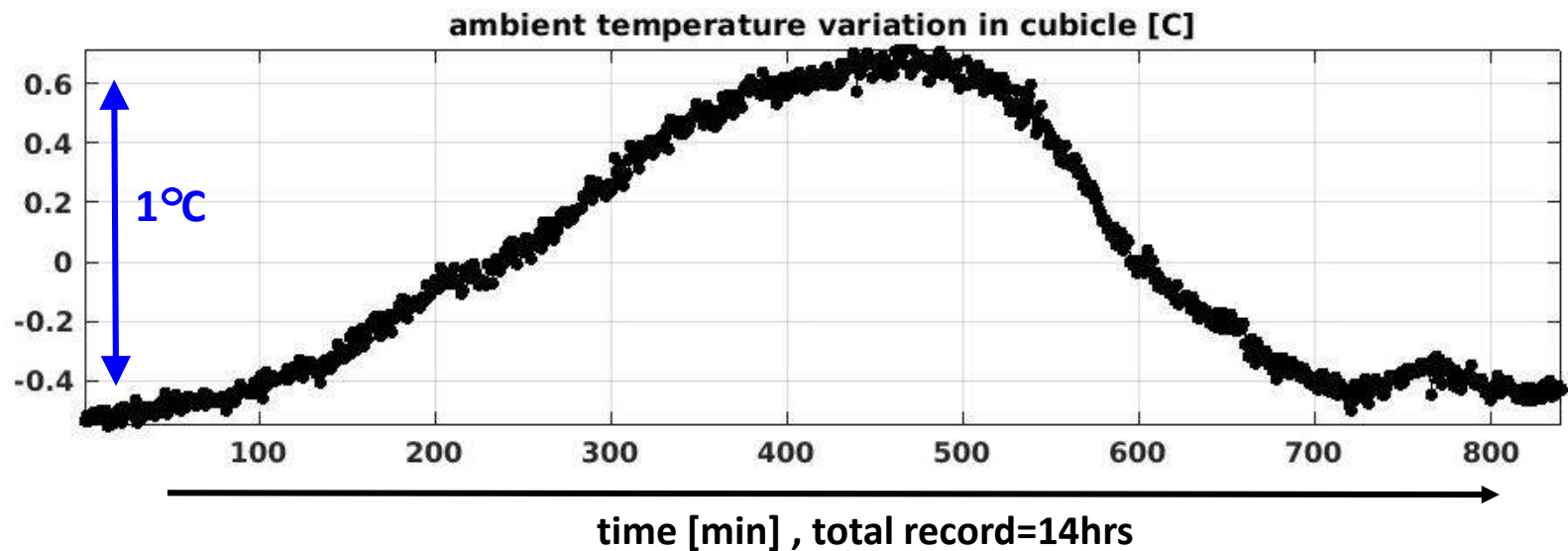
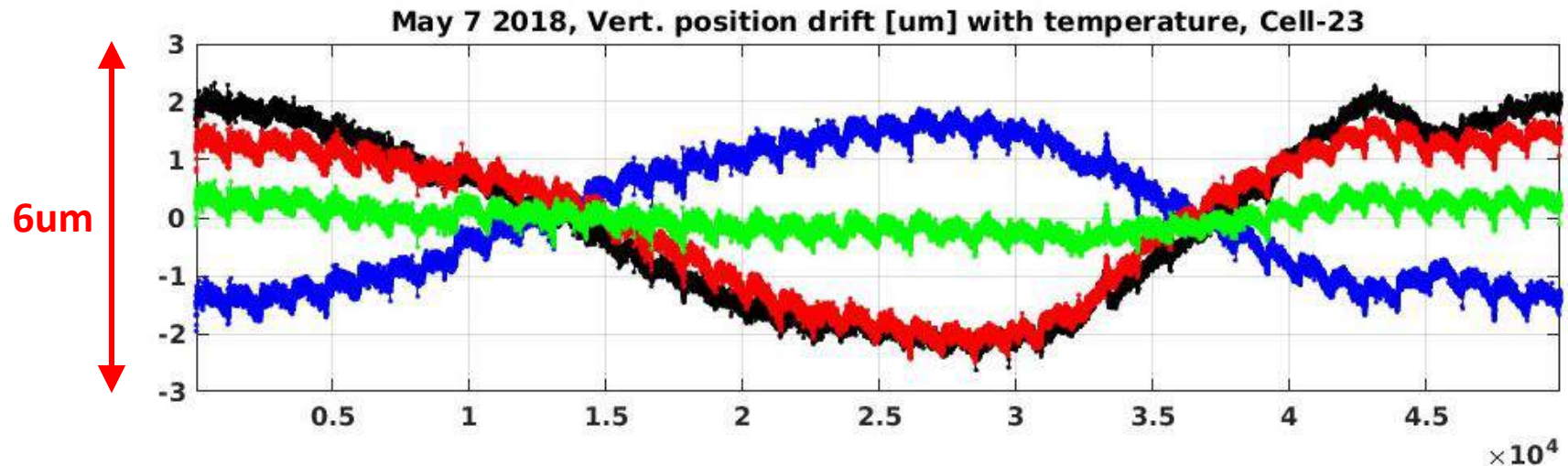
vert. is worse than hor. ?

average temperature drifts (vert.) : 2.1 , 6.0 , 1.2 , 3.7  $\mu m/C$

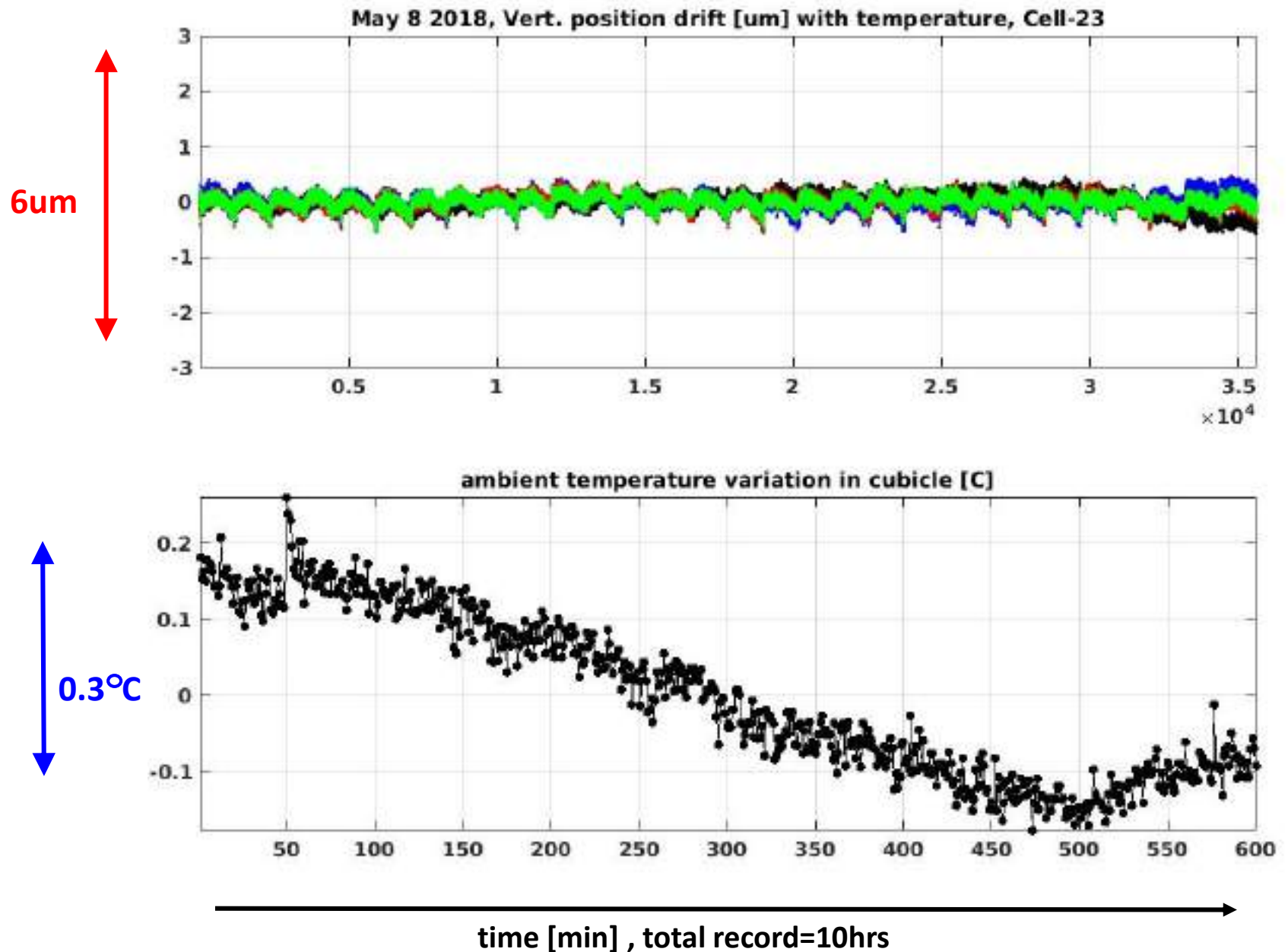


reminder :  
stab/temp.  
specification  
of Spark =  
3um/C

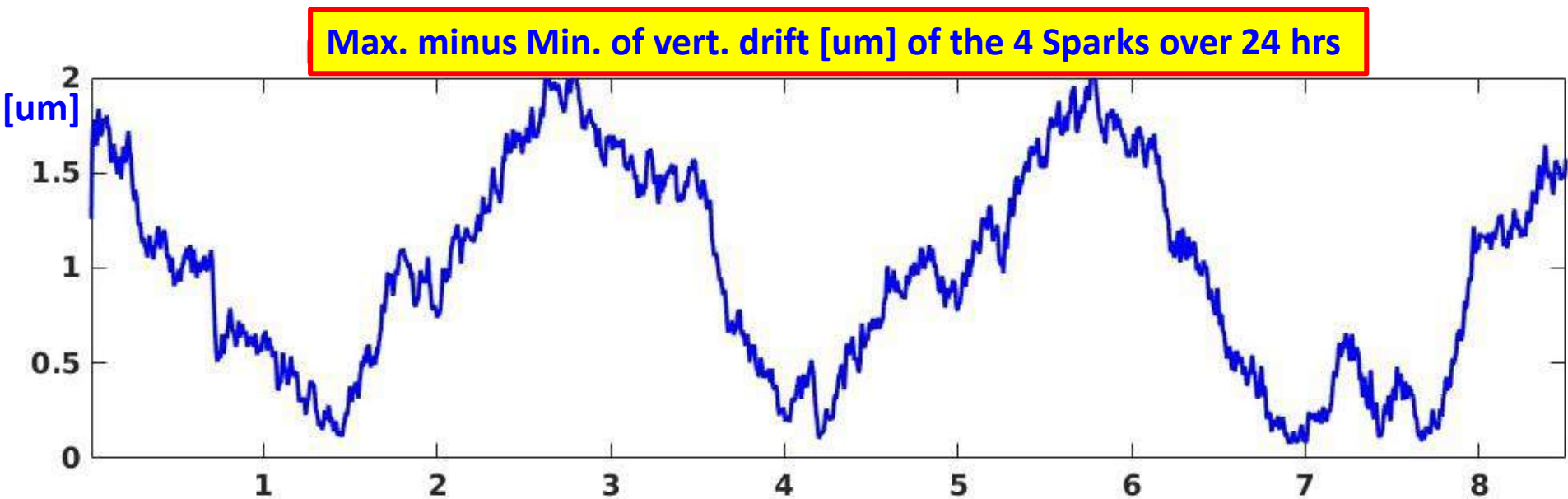
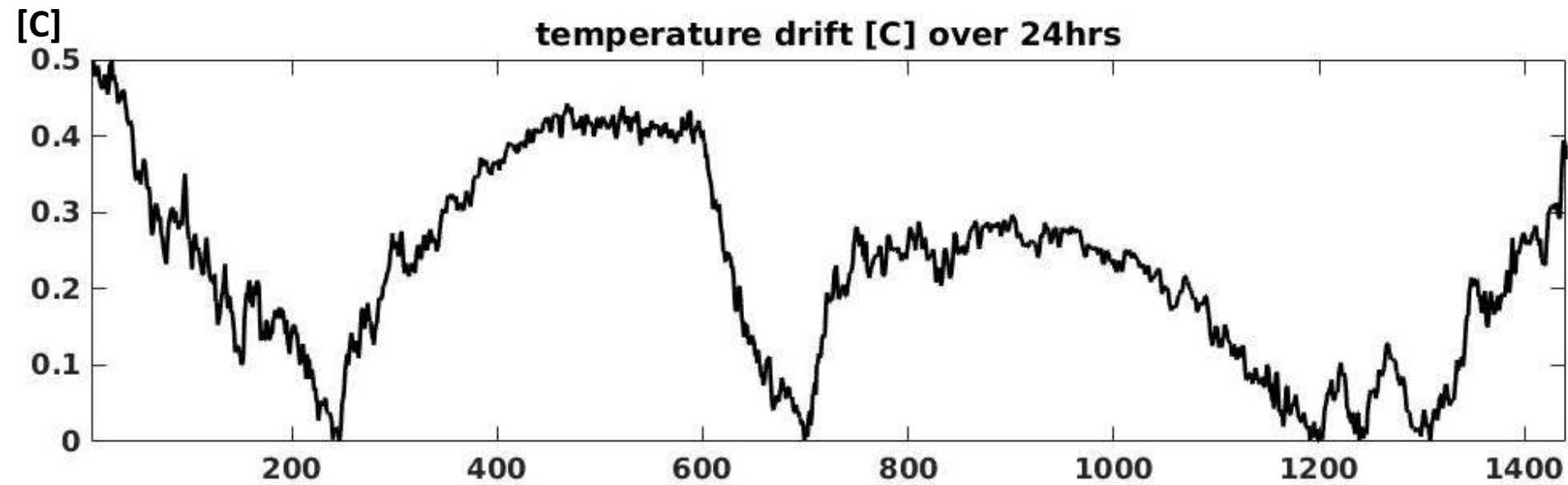
**strong** temperature fluctuations → **difficult** to assess the **long-term stability**  
in the cubicles i.e. **independent of temperature**



**weaker** temperature fluctuations → trying to assess the long-term stability  
in the cubicles i.e. independent of temperature



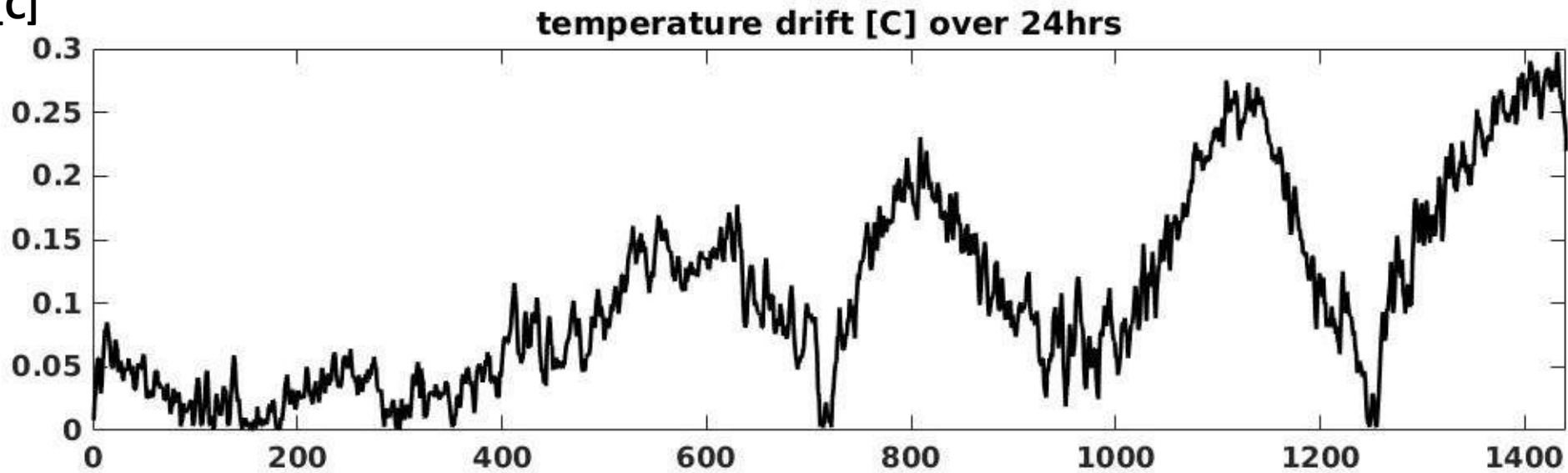
**strong** temperature fluctuations → **difficult** to assess the long-term stability  
in the cubicles i.e. independent of temperature



**weaker** temperature fluctuations  
in the cubicles

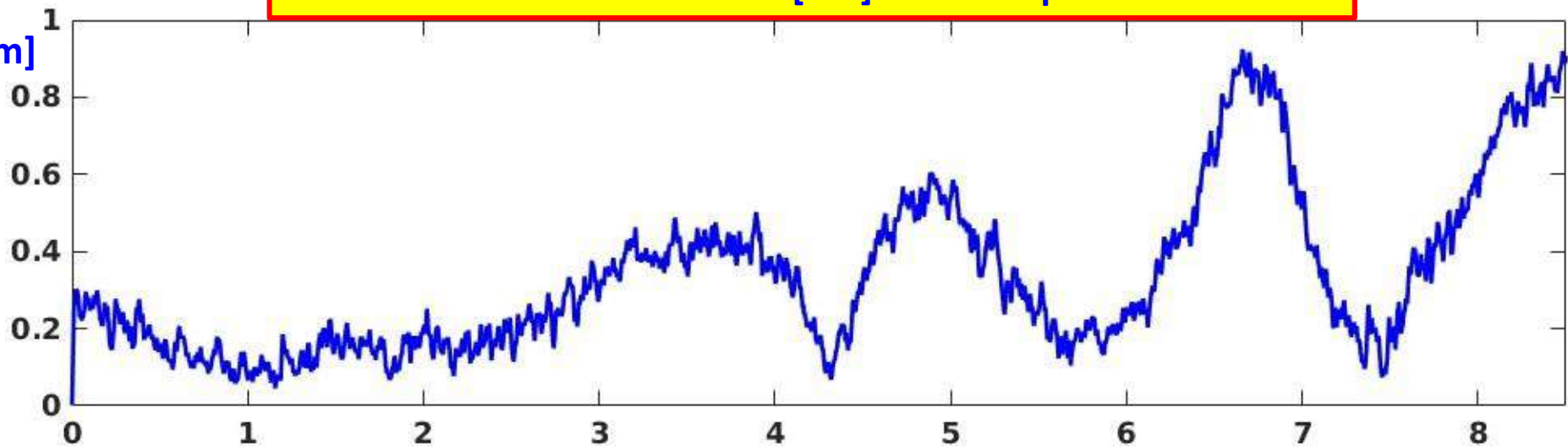
→ trying to assess the long-term stability  
i.e. independent of temperature

[C]



**Max. minus Min. of vert. drift [ $\mu\text{m}$ ] of the 4 Sparks over 24 hrs**

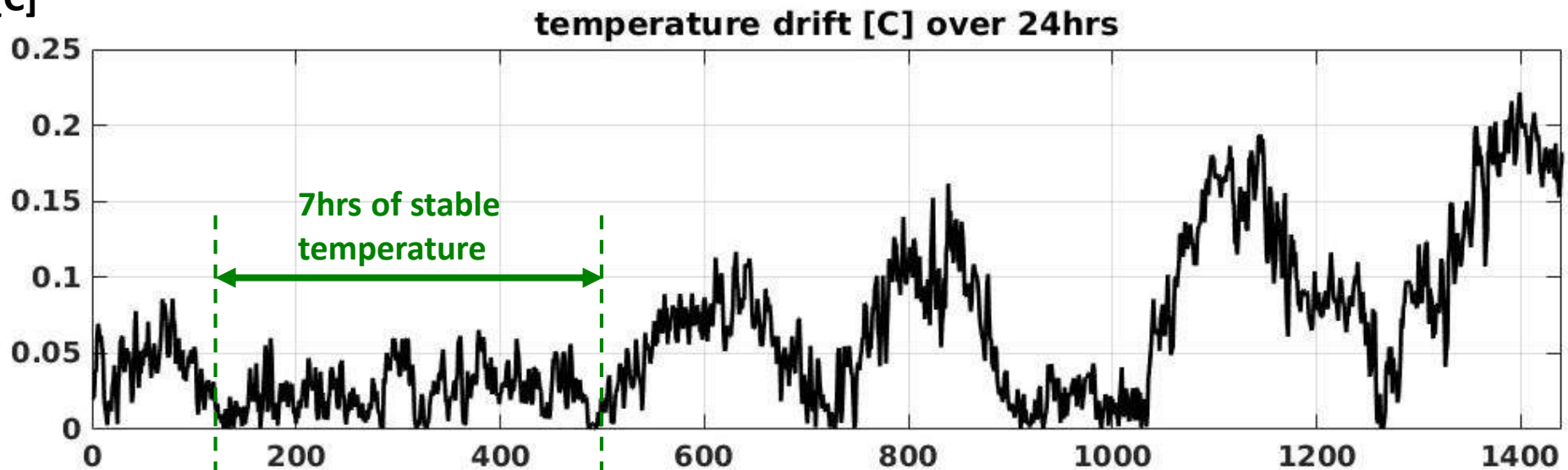
[ $\mu\text{m}$ ]



**weaker** temperature fluctuations  
in the cubicles

→ trying to assess the long-term stability  
i.e. independent of temperature

[C]



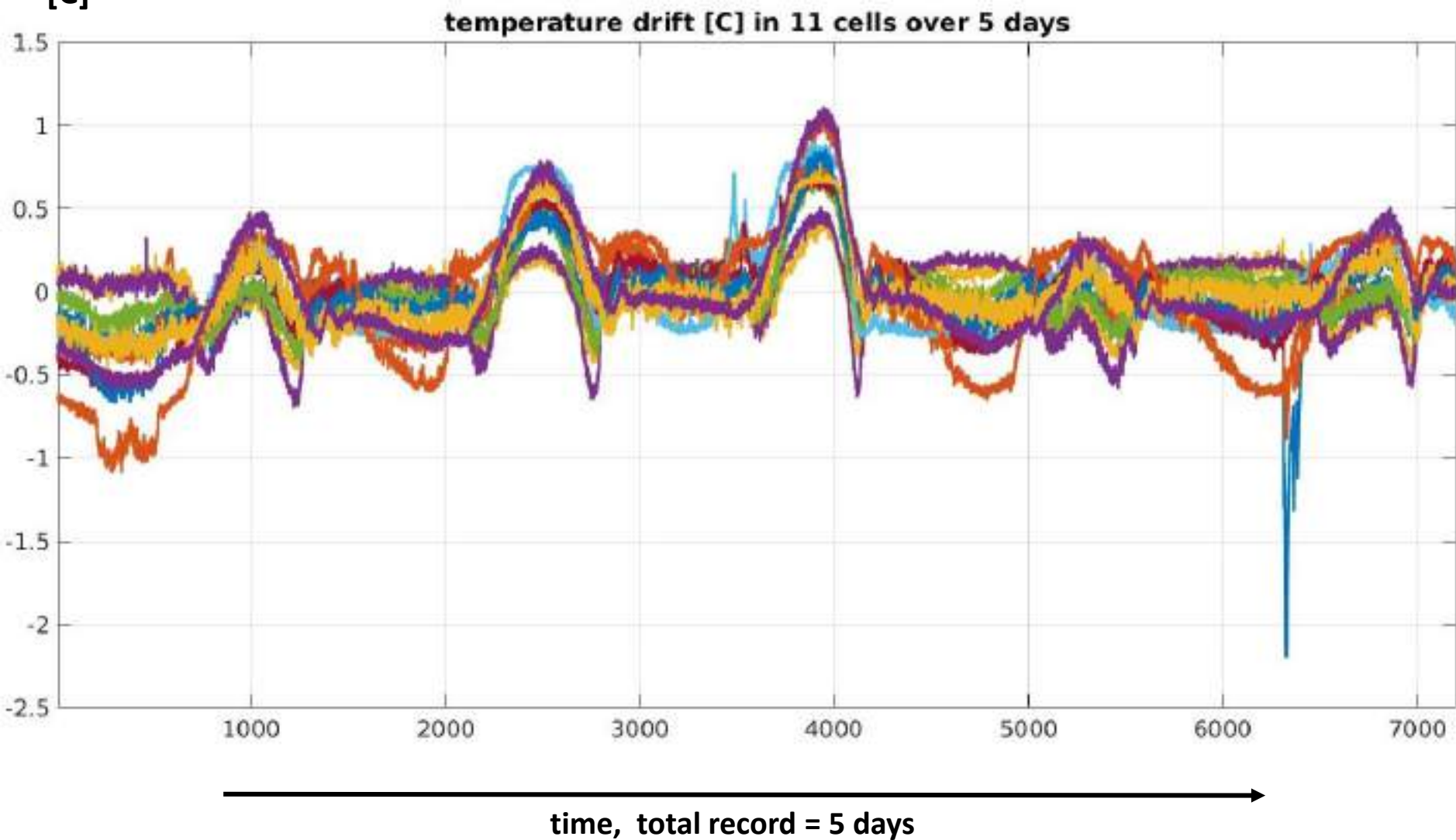
**Max. minus Min. of vert. drift [ $\mu\text{m}$ ] of the 4 Sparks over 24 hrs**

[ $\mu\text{m}$ ]

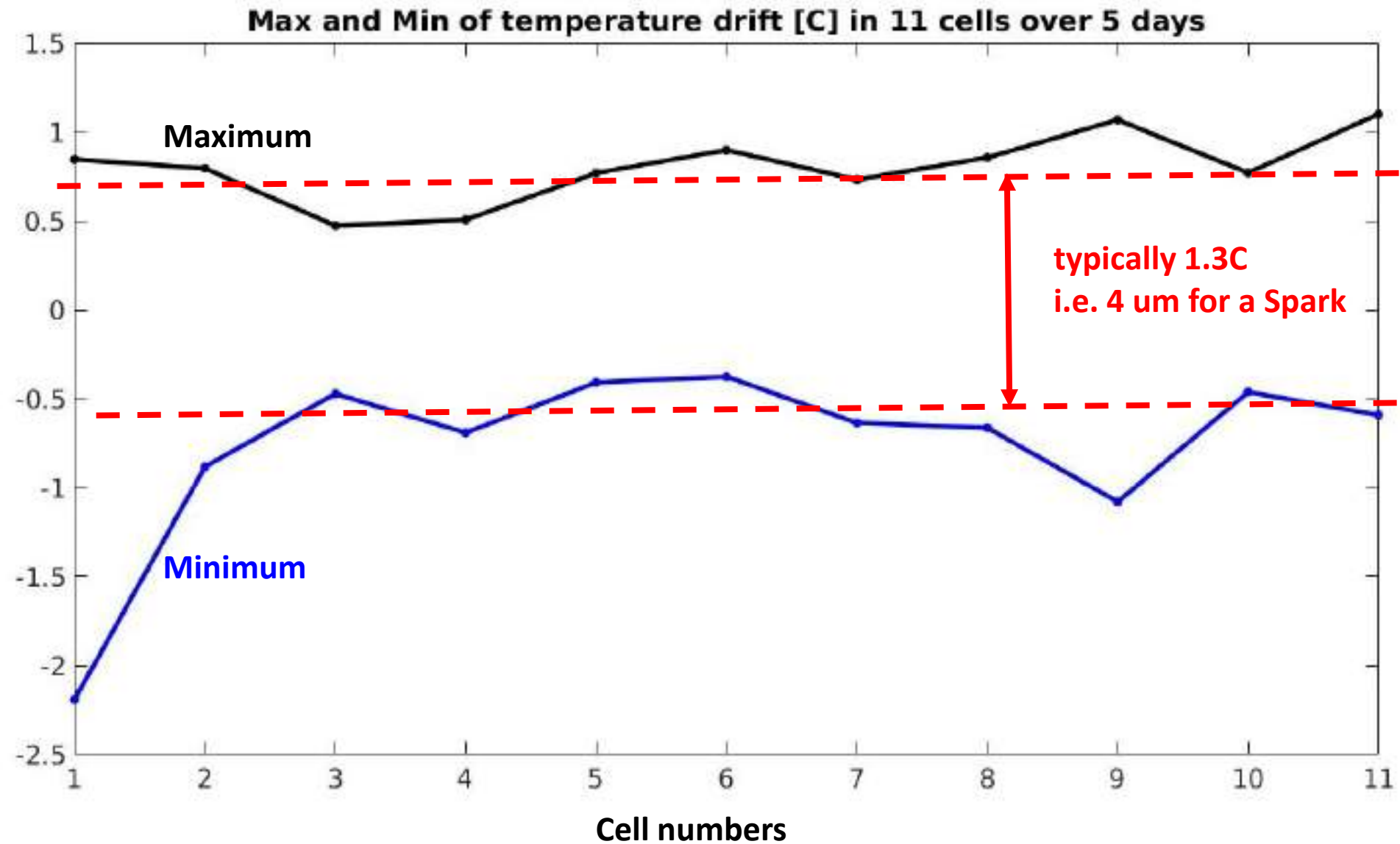


## 5 days temperature-drift recordings in the 11 cubicles

[c]



obviously ESRF needs better temperature stability in its cubicles



**first conclusions on :**

- 1) Stability vs temperature :**    **3um/C is respected :**    **many much better,  
some a bit worse**
- 2) Mid- Long- term stability :**    **excellent, estimation is well below 1um**
- 3) Reliability :**    **excellent**  
    incl. software :  
    I-Tech Tango server inside device  
    + ESRF group-server

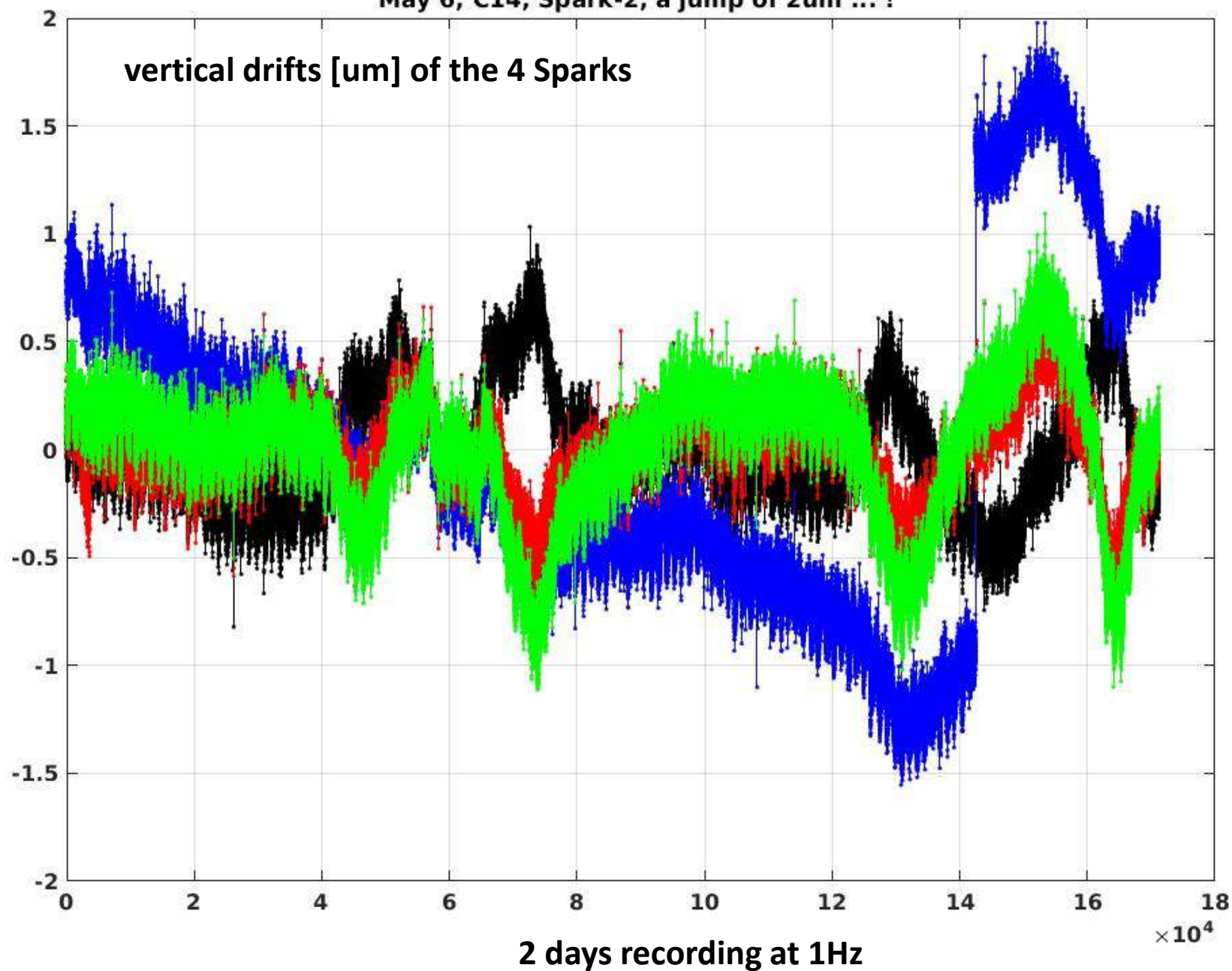
**for the ESRF (at present) : temperature drifts in cubicles dominate stability  
→ we need to get a better control of that**

**then stability & reproducibility issues, of the BPM-electronics,  
will all be minor & negligible, i.e. <1um**

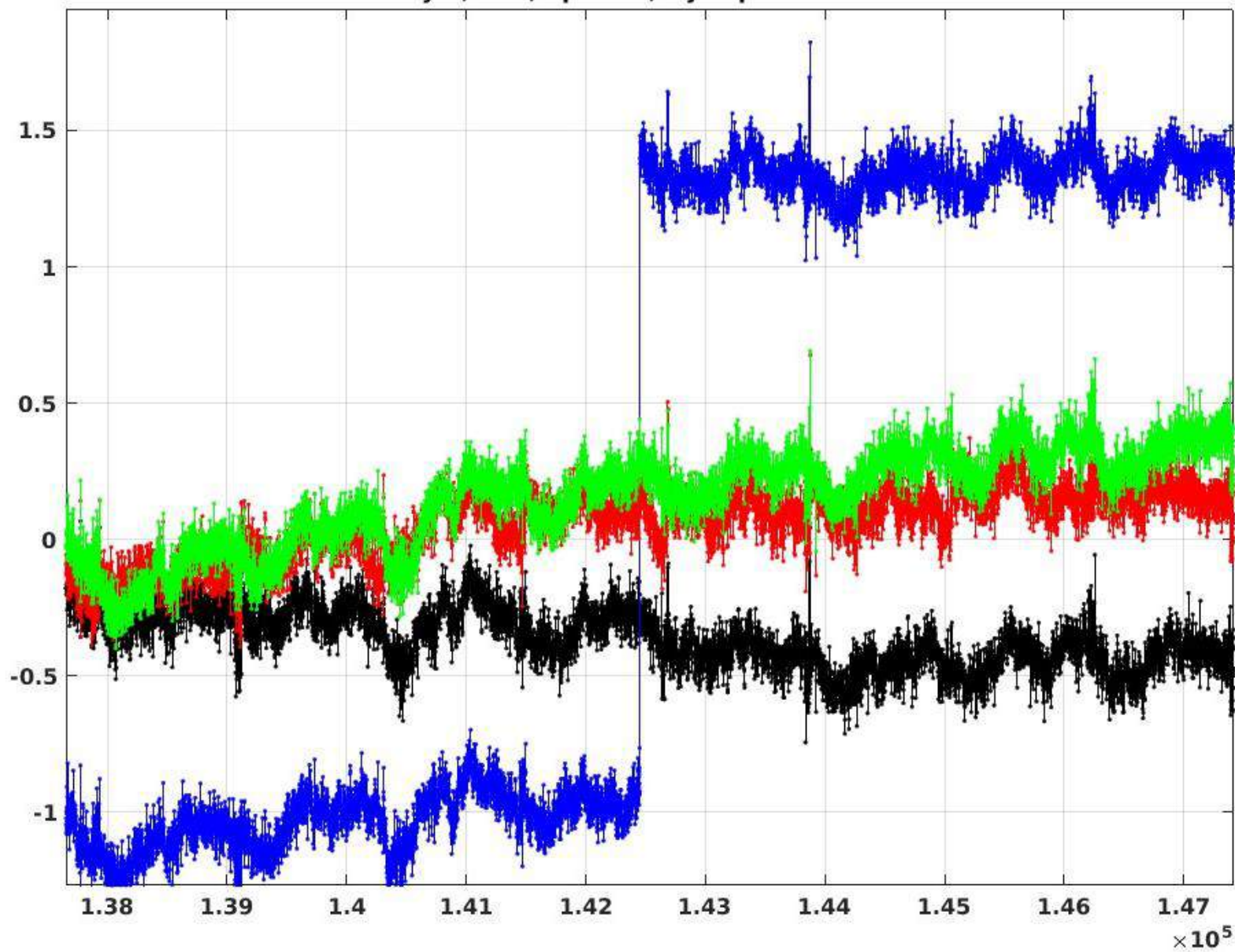
**but there is a snake ...**



May 6, C14, Spark-2, a jump of 2um ... !



May 6, C14, Spark-2, a jump of 2um ... !



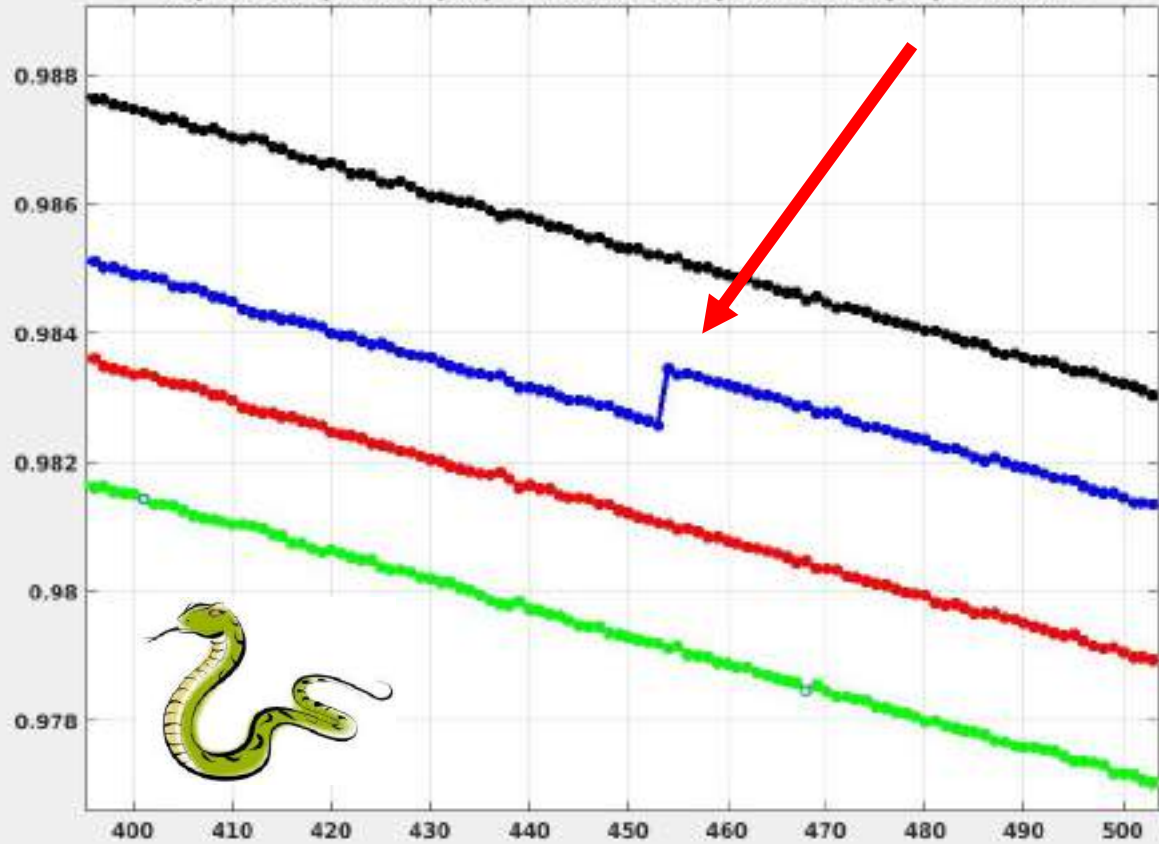
May 6, C14, Spark-2, a jump of 2um, caused by Ch.B (blue)

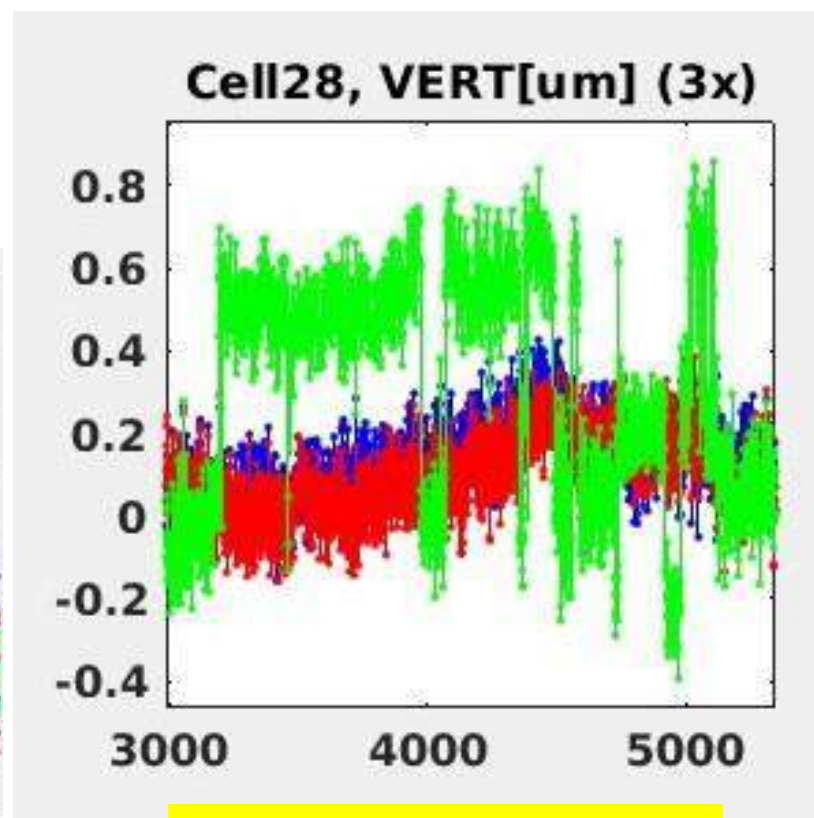
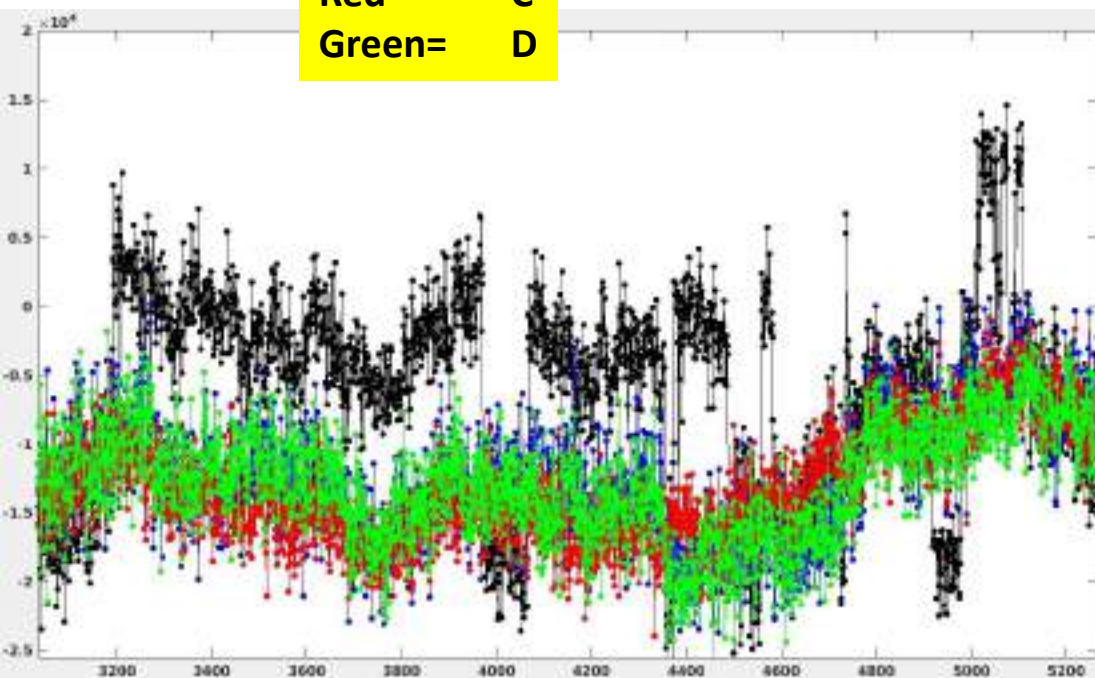
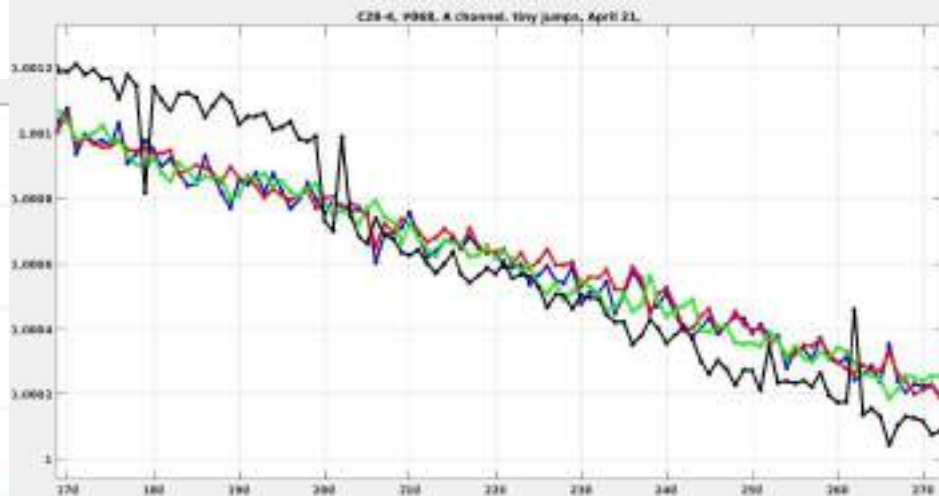
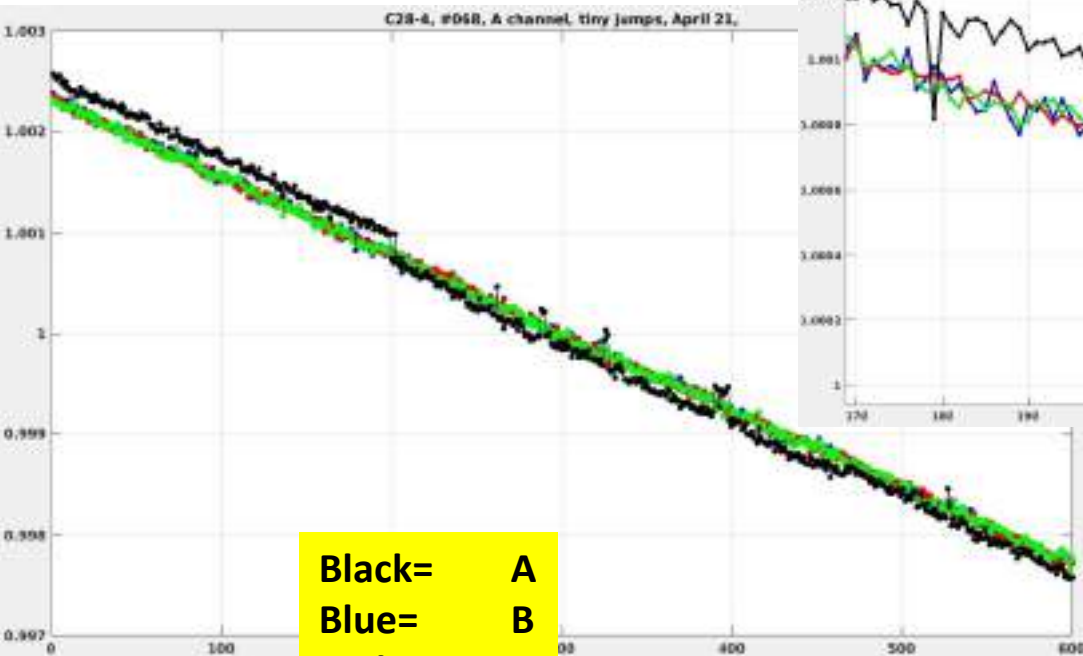


then we look at the  
A B C D data  
of that Spark ....

0.1% jump at Ch. B

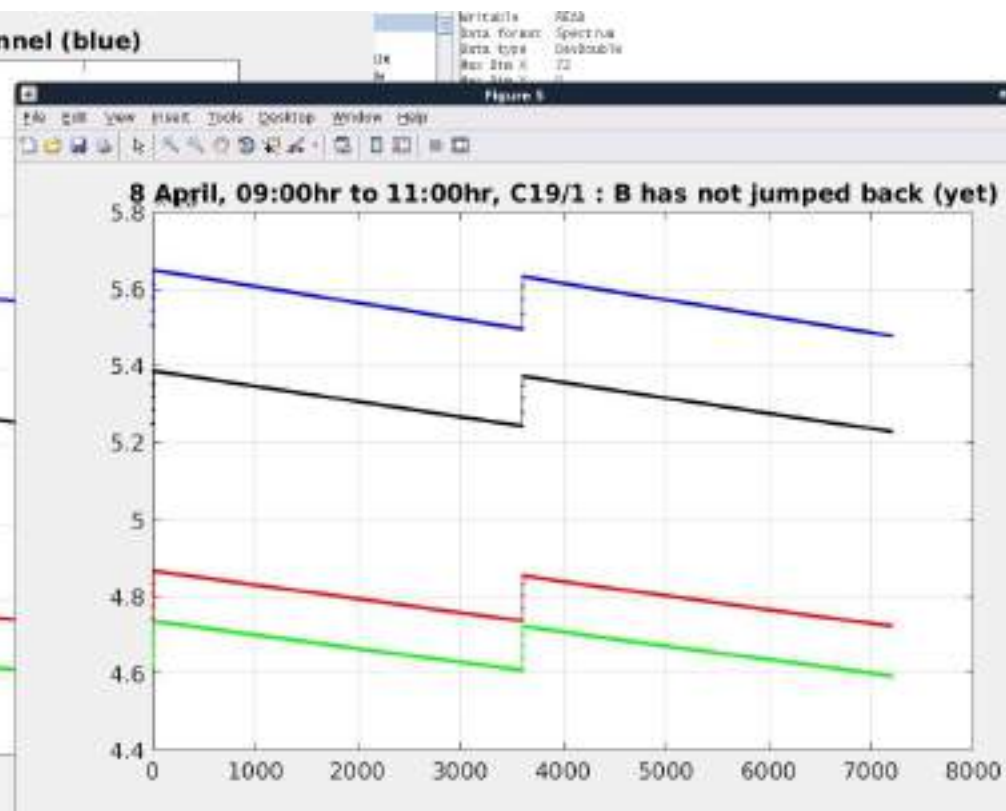
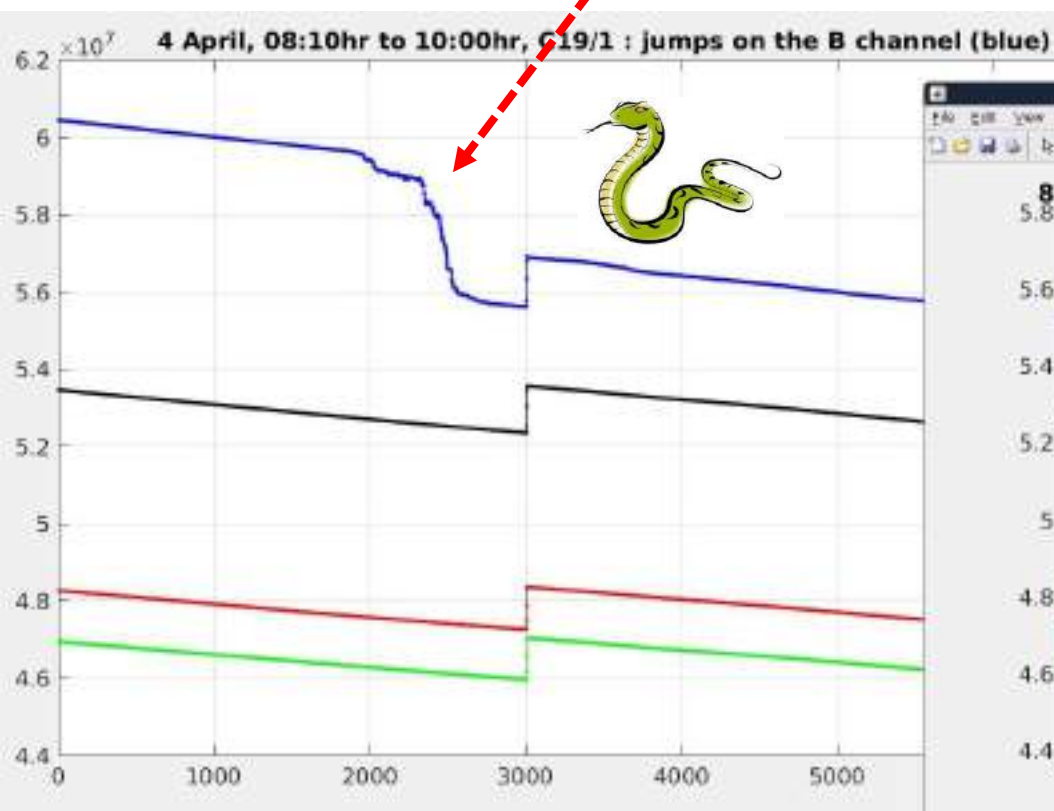
May 6, C14, Spark-2, a jump of 2um, caused by Ch.B (blue), jump of 0.1% ...



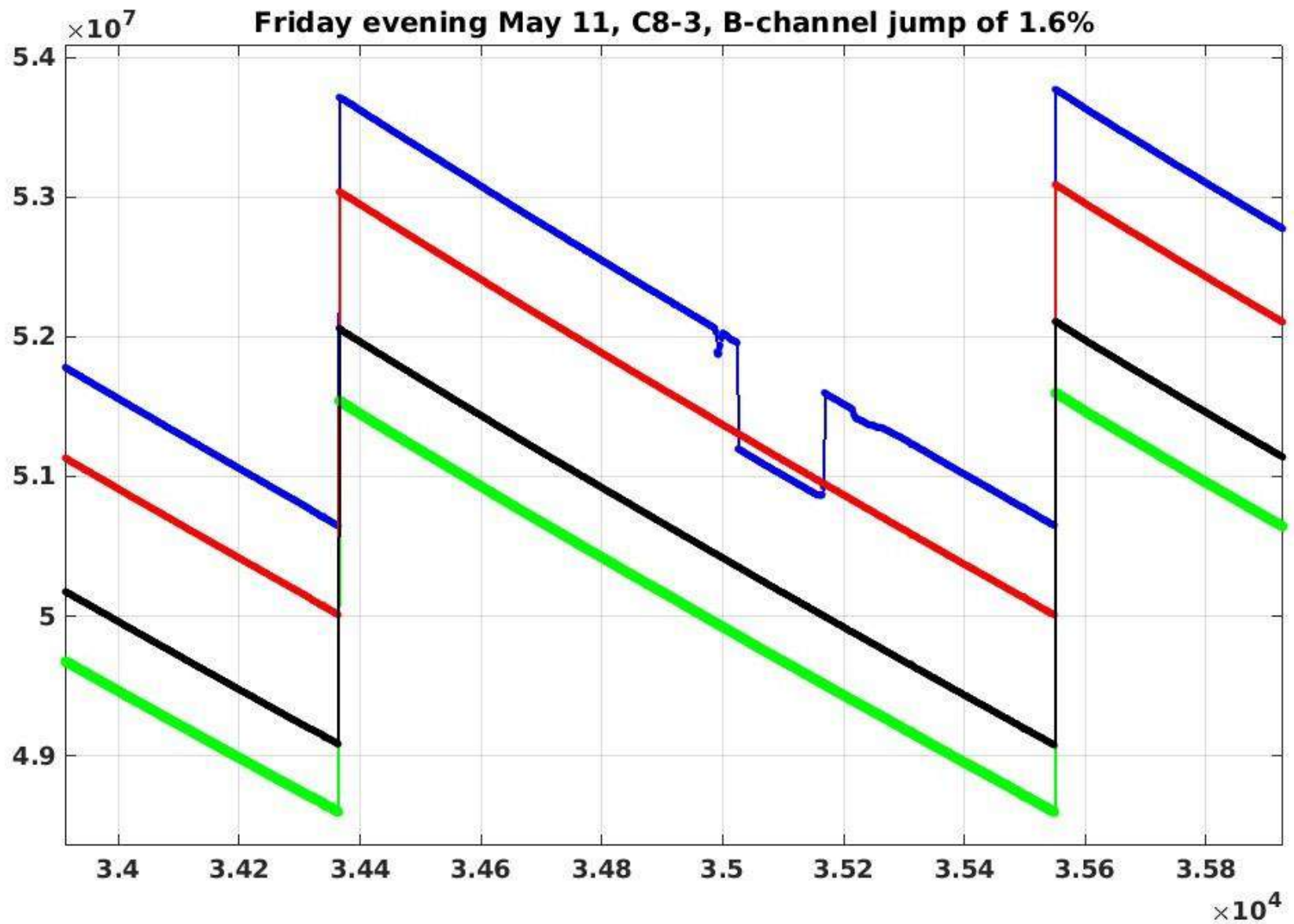


vert. pos [um] : green=#068,  
blue & red are neighbours

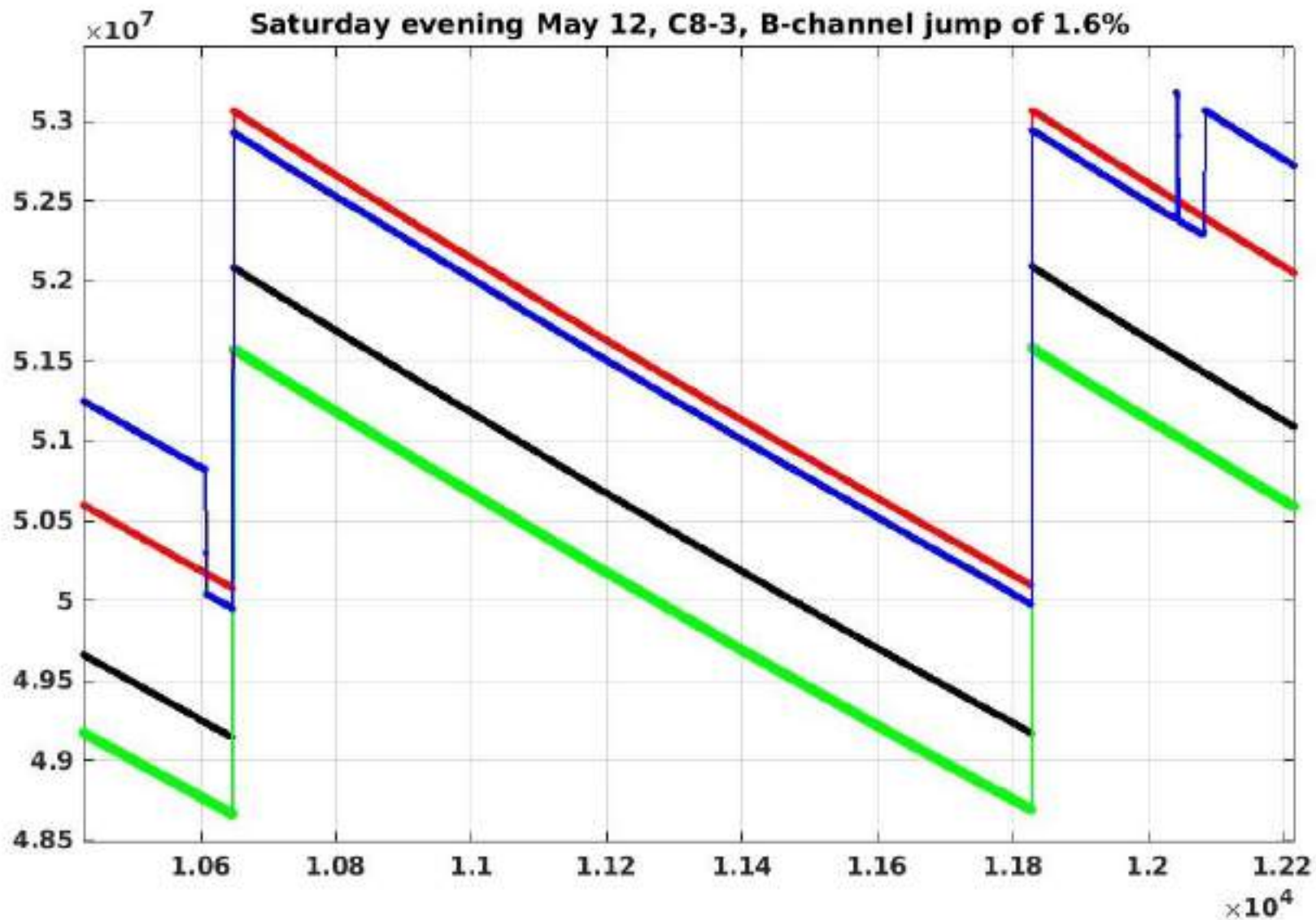
6% "jump" at Ch. B



latest events (May 11), another unit ....



latest events, one day later, May 12, same unit ....



- in total now : 88 Sparks in operation = 352 channels
- started in February with 20 Sparks, followed by progressive installation
- A B C D data stored at 1Hz

→ estimation of 4500 Spark • Days recordings  
 → equals :  $4500 \times 24 \times 3600 \times 4 = 1.5 \text{ E9 samples}$

we found about 8 “jumps” : twice on C14-2, Ch.B  
 twice on C8-3, Ch.B  
 and 4 other units (Ch.A or Ch.B ...)

**only channels  
A or B ... so far !**

these “jumps” are tiny or small (a um to 100um)

RF-splitters and/or RF-cabling an unlikely possible cause (but not 100% excluded)

how to deal with this ? :

- 1) **keep on checking in 2018**, some units may be removed/repared
- 2) once with beam (2020 and beyond) any detection of these jumps will be difficult, i.e. to clearly distinguish from real beam motion, but **surveying** the  $Q^*$  will allow to detect the worst ones
- 3) **trouble-shooting** the real cause by **the company, by lab tests & manipulations**



\*  $Q = A+C-B-D / (A+B+C+D)$  → does NOT vary (much) with beam motion  
 → but jumps when one channel jumps

## other (non-) features :

**1) for EBS the BPM-interlocks** will (only) be dealt with by Liberas  
i.e. NO implementation of interlocks in Sparks  
same for **Post-Mortem buffers** : NONE in Spark

**None !**

### **2) Gain / Attenuator control :**

NO AGC inside Spark (individually) → will be dealt with by external server/application  
one common attenuator setting for each of the 4 channels (0 to 31 dB)

**Keep it Simple !**

**3) minimizing steps/jumps** in position results when **changing attenuation**  
**calibration feature** implemented :

is **simple & efficient** but requires **particular RF input signals**  
how stable is this with time ?

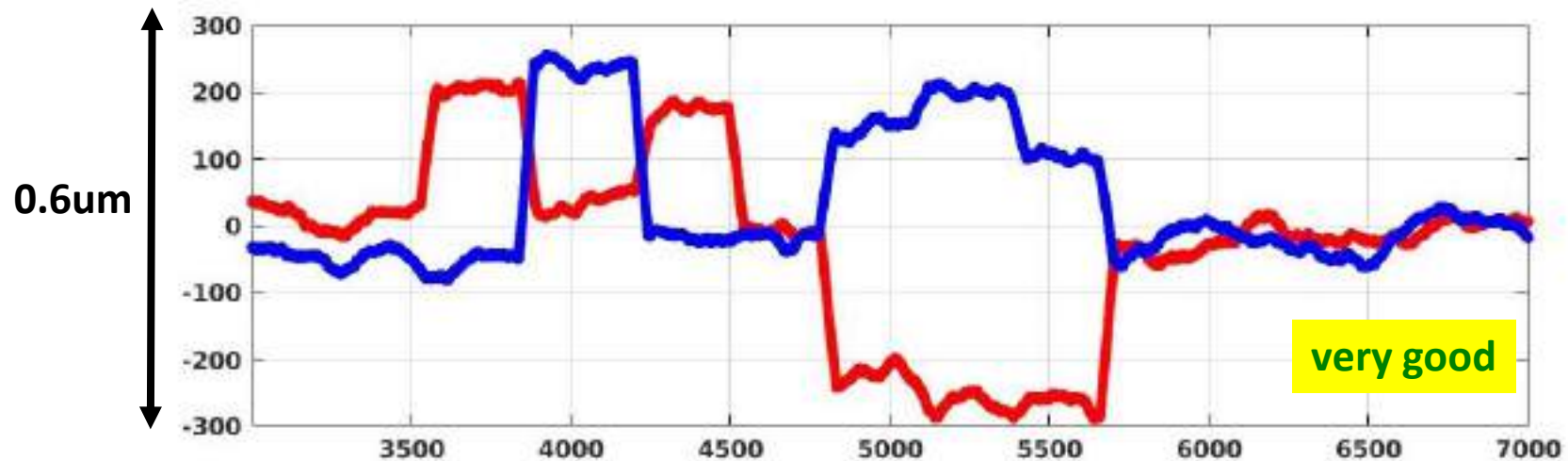
**simple & efficient !**

see next slides :

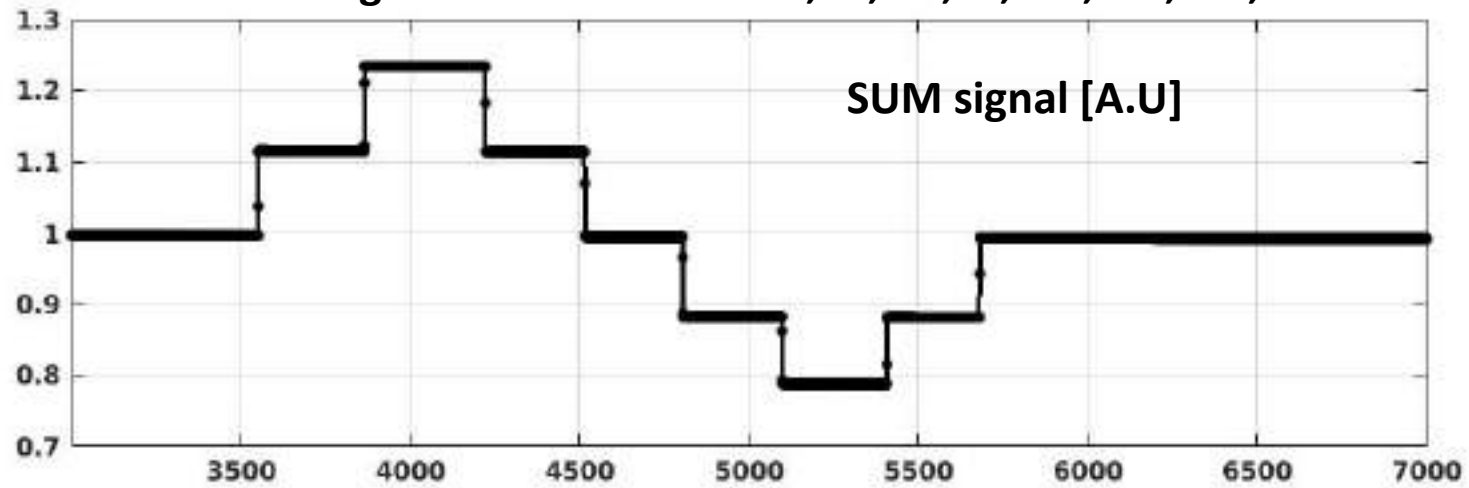
calibration data on all 4 x 32 attenuator settings were defined at SATs  
we did NOT change (recalibrate) them, so let's see the effect now (months later)

**let's check ....**

2 units , among the best ones, vertical position [nm]

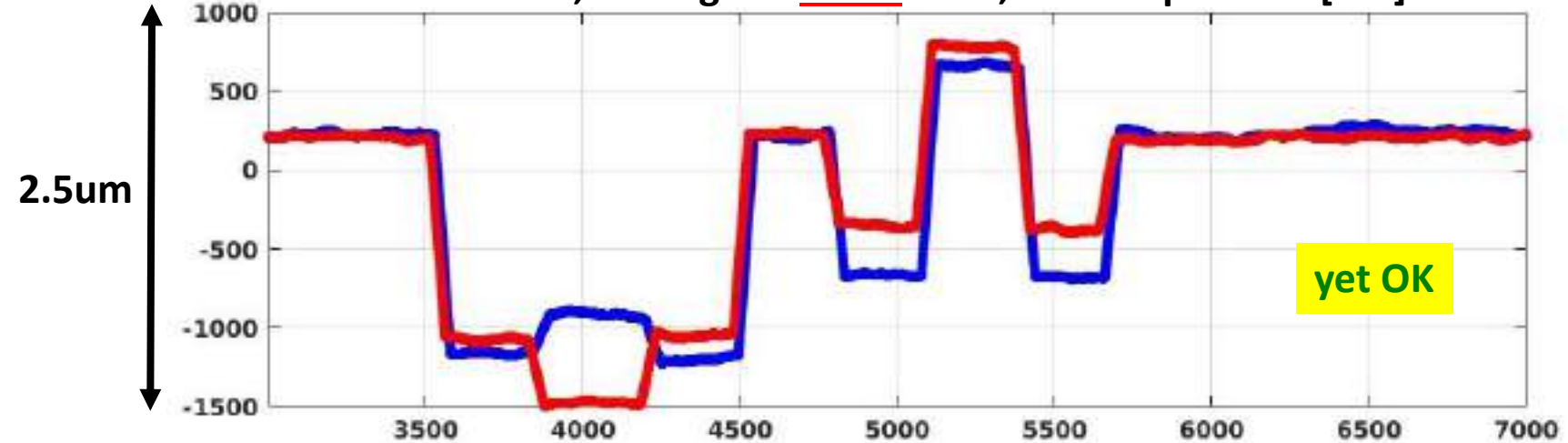


7 changes of attenuation : -1 , -2, -1, 0, +1, +2, +1, 0 dB

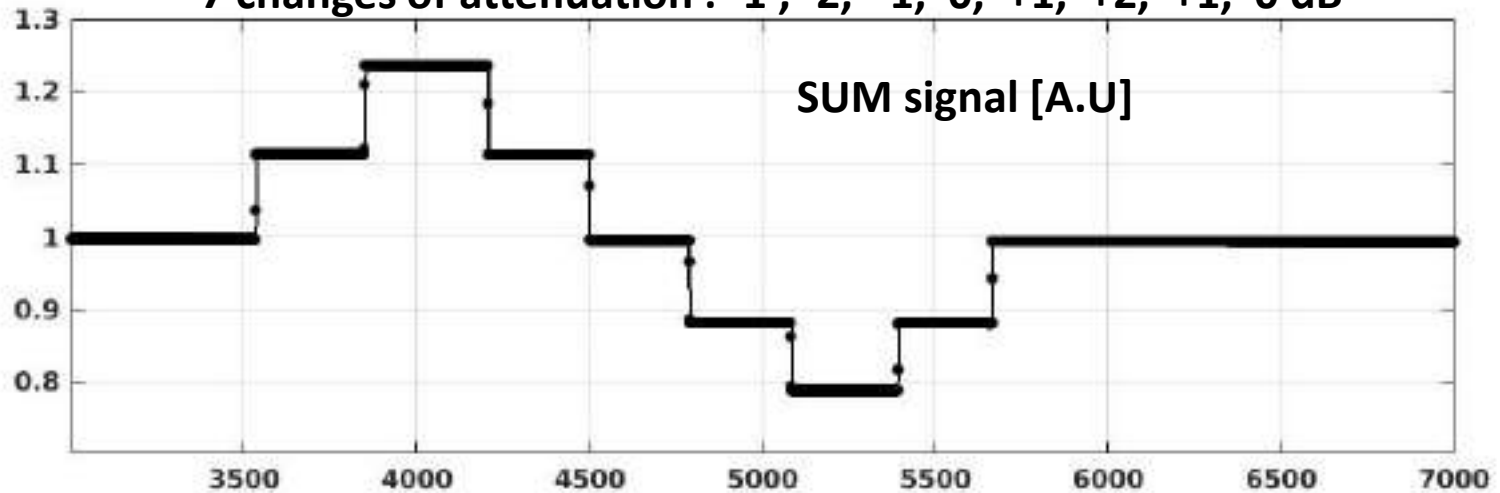


time, about 2 minutes

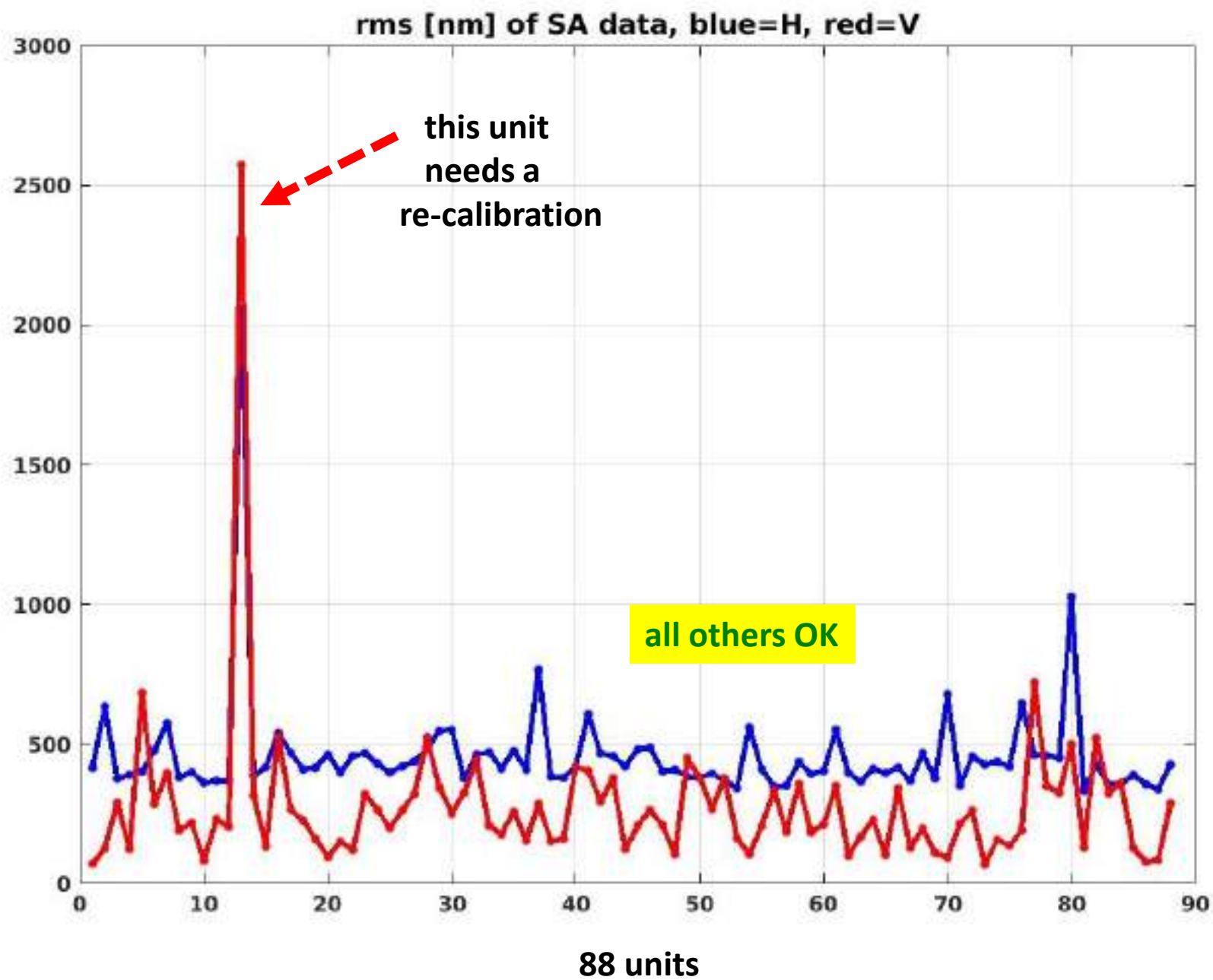
2 units , among the worst ones, vertical position [nm]



7 changes of attenuation : -1 , -2, -1, 0, +1, +2, +1, 0 dB

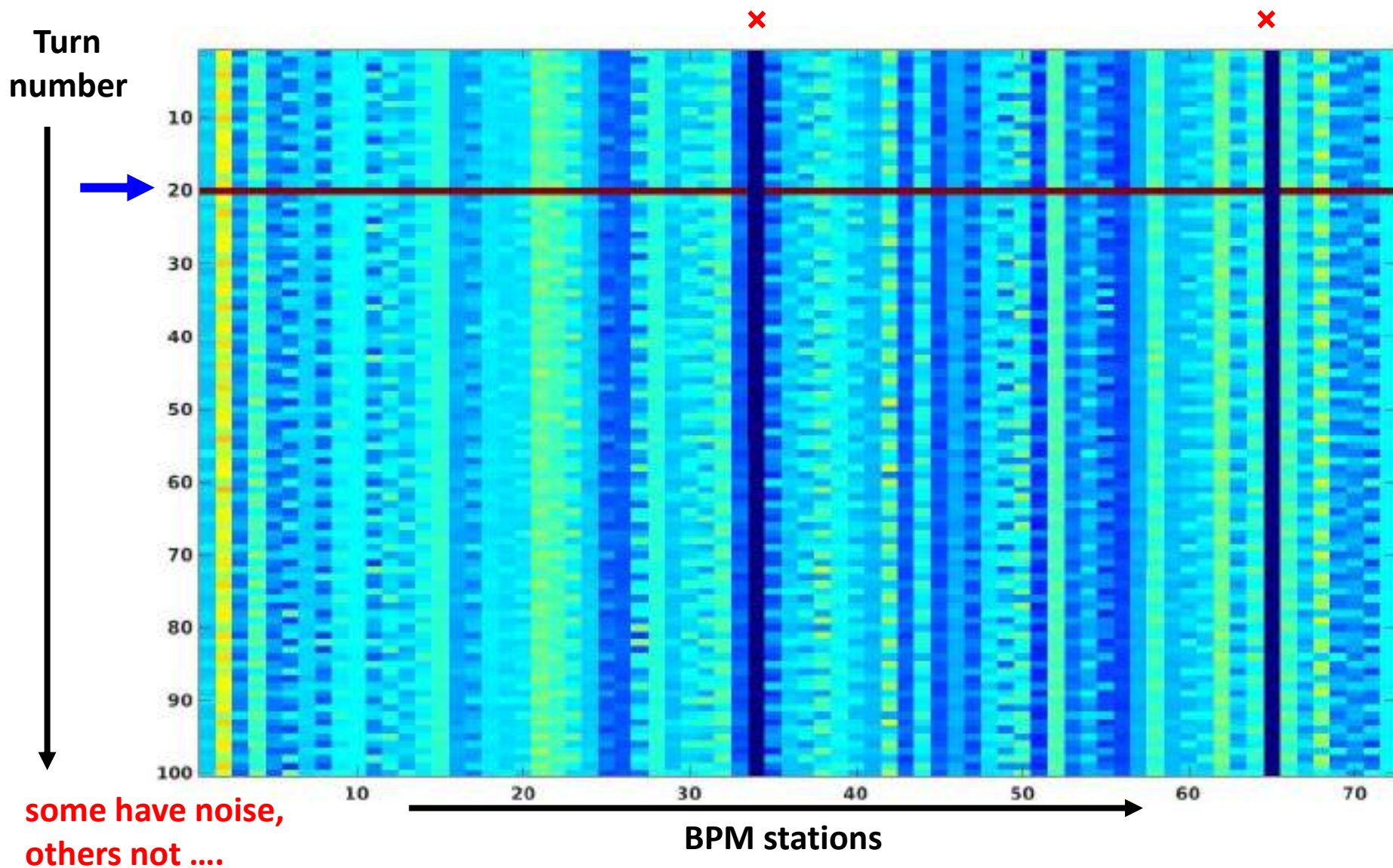


time, about 2 minutes

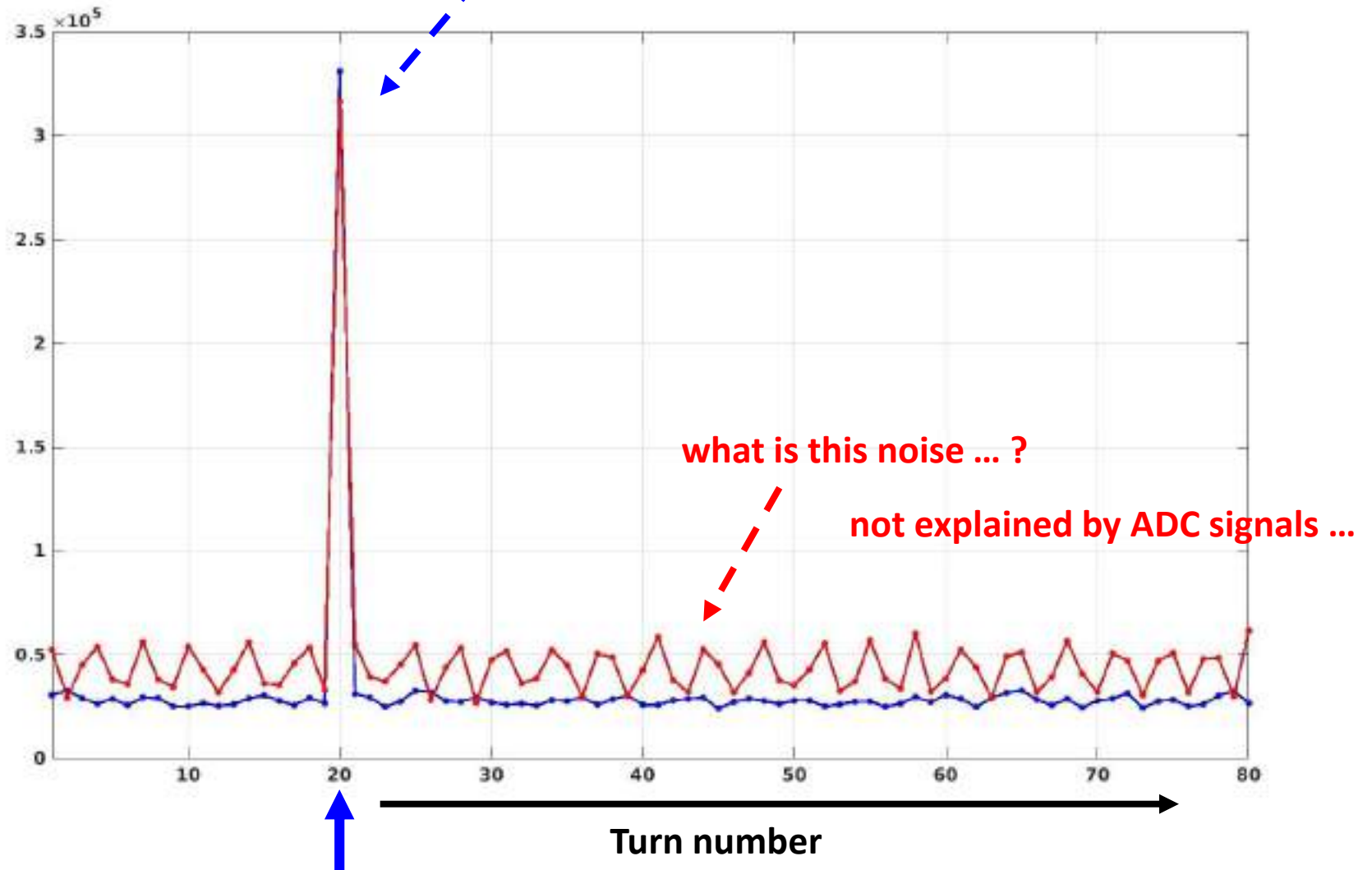


Turn-by-Turn data, synchronization OK, but .... weird effect when buffers enabled

SUM TDP at Injection, making only one Turn



SUM TDP at **Injection**, making only one Turn



File View

C04	C05	C06	C07	C08	C09	C10	C11	C12	C13	C14	C15	C16	C17	C18	C19	C20	C21	C22	C23	C24	C25	C26	C27	C28	C29	C30	C31	C32	C33	C34	C35

Settings 1 Settings 2 Detailed Settings XZ Position Max ADC

General		ADC		TET		TDF		TET IQ	
Trigger Source	External	ADC_Enabled	False	TET_Enabled	False	TDF_Enabled	False	TET_IQ_Enabled	False
Trigger Counter	17555	ADC_Mode	On Event	TET_Mode	On Event	TDF_Mode	On Event	TET_IQ_Mode	On Event
Attenuation	0	ADC_SubGain	1.00	TET_DeDco	1.00	TDF_DeDco	1.00	TET_IQ_DeDco	1.00
Gain Instinct	True	ADC_MaxOffset	0	TET_BT	0	TDF_BT	0	TET_IQ_BT	0
Gain Active	False	ADC_PostWindow	504	TET_Offset	0	TDF_Offset	0	TET_IQ_Offset	0
Gain Limit ADC	0	ADC_PostWindow	504	TET_Window_Enable	False	TDF_Window_Enable	False	TET_IQ_Window_Enable	False
Gain Limit Samples	40	ADC_Saturation	0	TET_Window_Mode	On Event	TDF_Window_Mode	On Event	TET_IQ_Window_Mode	On Event
Compensate Offset Time	True			TET_Window_Latency	0				
Offset	0								
VOffset	0								
Phase Offset	0								
Offset Time	0								
Set Offset	40								

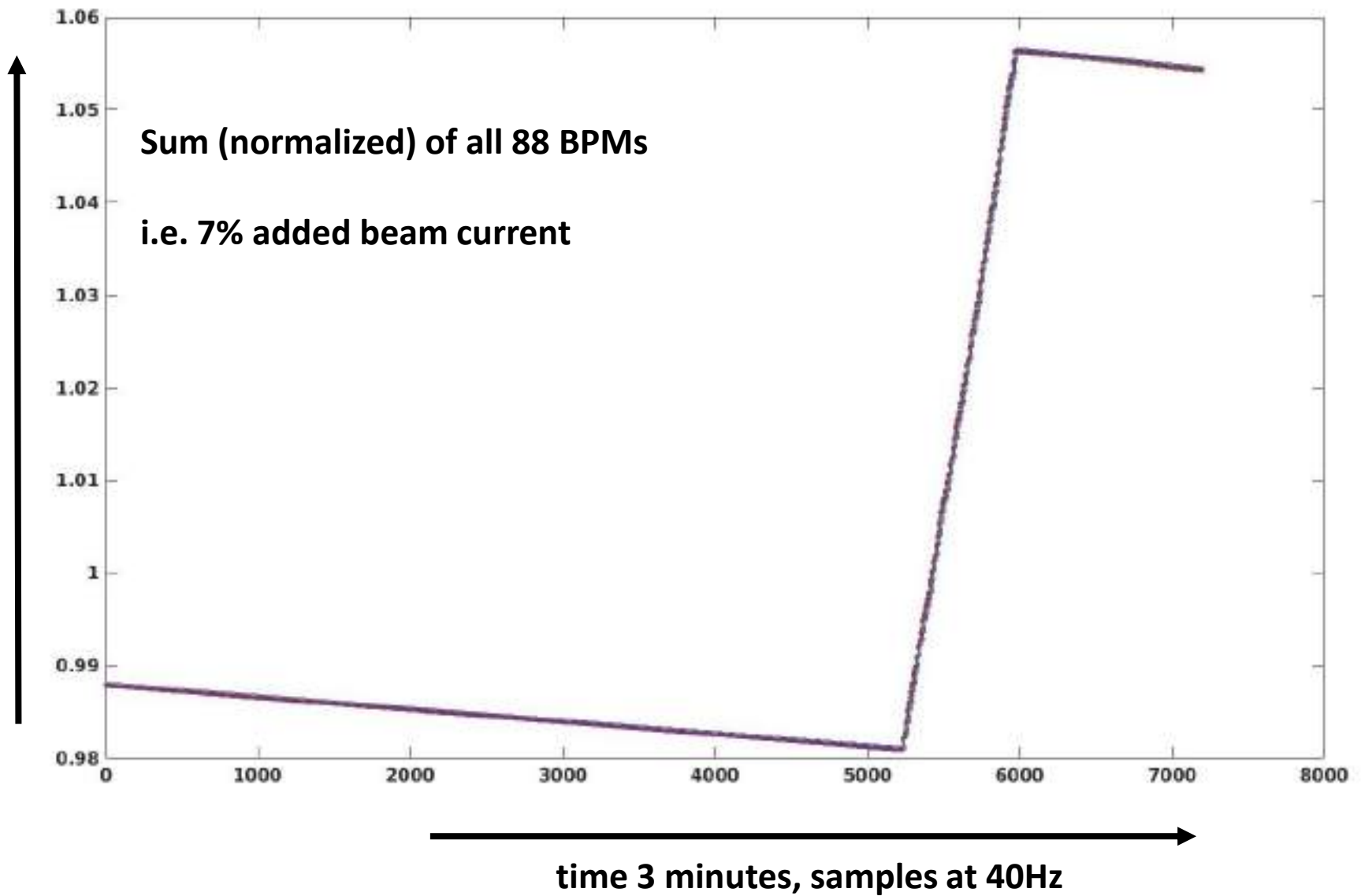
File View

C04	C05	C06	C07	C08	C09	C10	C11	C12	C13	C14	C15	C16	C17	C18	C19	C20	C21	C22	C23	C24	C25	C26	C27	C28	C29	C30	C31	C32	C33	C34	C35

Settings 1 Settings 2 Detailed Settings XZ Position Max ADC

SA		TET Decimated		TDF Decimated		TET IQ Decimated	
SA_Enabled	True	TET_Dec_Enabled	False	TDF_Dec_Enabled	False	TET_IQ_Dec_Enabled	False
SA_History_Enabled	True	TET_Dec_Mode	On Event	TDF_Dec_Mode	On Event	TET_IQ_Dec_Mode	On Event
SA_History_Mode	New	TET_Dec_SubGain	1.00	TDF_Dec_SubGain	1.00	TET_IQ_Dec_SubGain	1.00
SA_History_Offset	0	TET_Dec_BT	0	TDF_Dec_BT	0	TET_IQ_Dec_BT	0
		TET_Dec_Offset	0	TDF_Dec_Offset	0	TET_IQ_Dec_Offset	0

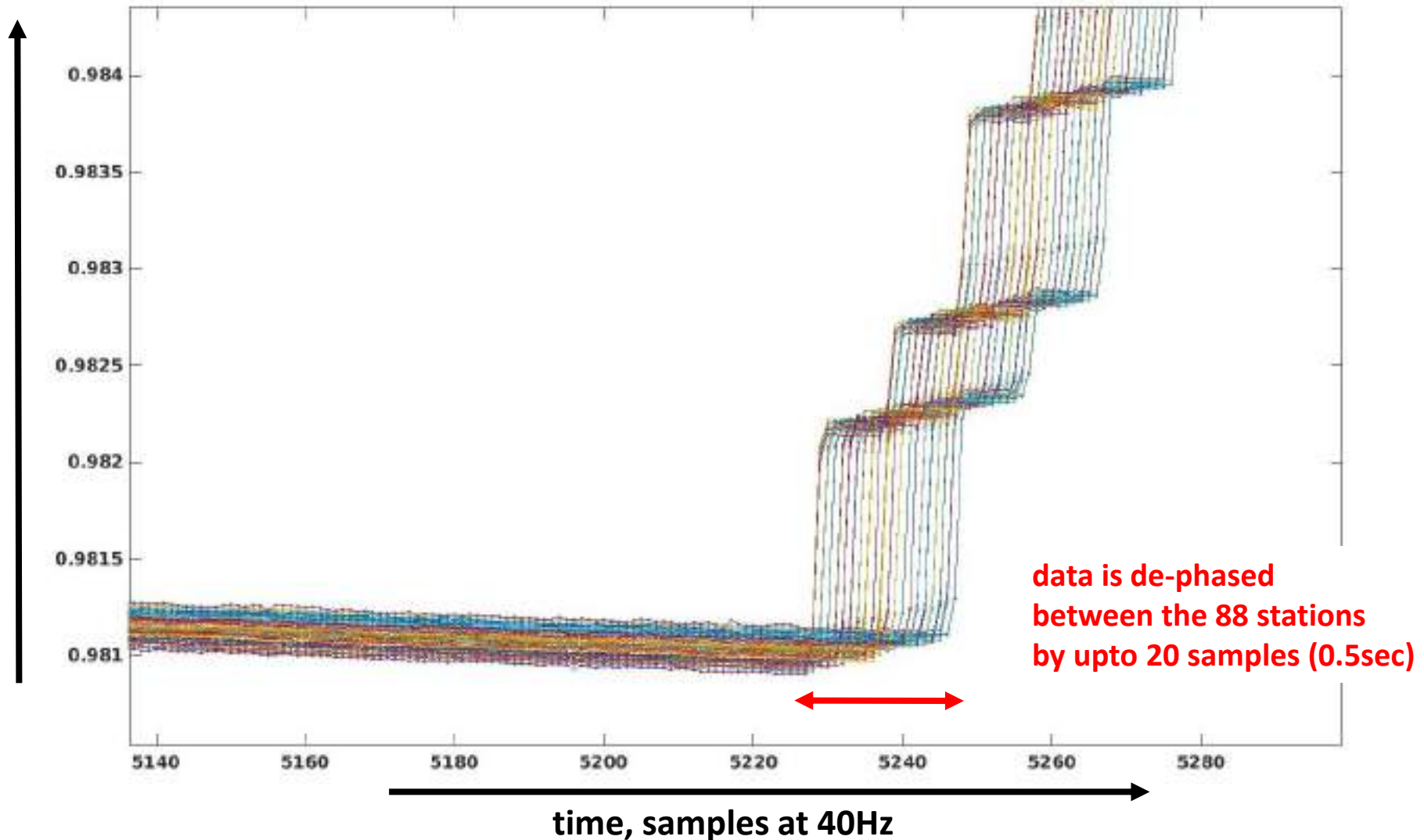
# SA-SUM-History data buffer, 40Hz, all 88 stations, at Injection



# SA-SUM-History data buffer, 40Hz, all 88 stations, at Injection

Sum (normalized)  
of all 88 BPM

this de-phased data in the 88 History buffers is annoying  
is it produced by the ESRF group-call server ... ?  
can it be avoided ? how ?



results with complete & permanent tests on  
128 Spark BPM electronics for ESRF's new L-E Ring  
on real RF-beam signals

*Thank you for your attention*