

## The Elettra Fast Global Orbit Feedback

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Sincrotrone Trieste - Elettra

Presented by M. Lonza

Marco Lonza, "The Elettra Fast Global Orbit Feedback"

"Libera Workshop" – Solkan, Slovenia , 24-25 September 2007

#### Milestones of the project



the existing RF BPM detectors have been replaced with Libera Electron:
 March 2006 - March 2007

installation of the feedback system: finished February 2007

Ioop closed in March 2007

sommissioning of the fast feedback system followed by:

- **u** optimization of the feedback parameters
- a development of control room panels
- Set definition and implementation of the operational procedures

since beginning of September 2007 the feedback is routinely used during users shifts

Marco Lonza, "The Elettra Fast Global Orbit Feedback"

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#### Marco Lonza, "The Elettra Fast Global Orbit Feedback"

**Diode Detector unit** 

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## **BPM Detectors Upgrade**

Sector Se

Negligible inconvenience to machine operations and beam line experiments

The fast orbit interlock system (protection of the vacuum chamber from synchrotron radiation) based on the old BPM detectors has also been replaced

The new interlock has a redundant architecture using Libera detectors and newly developed diode detectors all connected to a Programmable Logic Controller (PLC)

 States
 Logs

 Ibera BPM 1
 Ibbera BPM 2
 Diode BPM ID Status
 Intercorr

 ID\_S12W
 IL2.6: NORMAL
 IL1: NORMAL
 NORMAL
 CLOSED
 ENABLED

 ID\_S12W
 IL2.6: NORMAL
 IL1: NORMAL
 NORMAL
 OPEN
 DISABLED

 ID\_S12W
 IL2.6: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED

 ID\_S12W
 IL3: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED

 IL3.3: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED
 1>20mA

 IL4.3: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED
 1>20mA

 ID\_70
 IG.3: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED
 1>20mA

 ID\_71
 IG.3: NORMAL
 IL4: NORMAL
 NORMAL
 OPEN
 DISABLED
 1>20mA

 ID\_71
 IG.3: NORMAL
 IL4: NORMAL
 NORMAL
 NORMAL
 OPEN
 DISABLED
 I>20mA

 ID\_71
 IG.3: NORMAL
 IL4: NORMAL
 NORMAL
 NORMAL
 OPEN
 DISABLED
 I>20mA

 ID\_71
 IG.3: NORMAL
 IL4: NORMAL</t

Supervisor of the orbit interlock system



PLC of the orbit interlock system





## **Global Orbit Feedback Architecture**



**a** 82 corrector magnets per plane

**u** 12 + 1 VME GOF stations with Motorola 6100 CPU boards running Linux (Tango control system) and RTAI real-time extension (feedback processing)

- Sigabit Ethernet to acquire 10 kHz data from Libera Electron
- **u** Reflective Memory to share data in real-time: 13 PMC modules, fibre optics
- PMC DAC modules to convert corrections to analog

**Solution** Event system: 1 EVG, 12 EVR, Libera Clock Splitters and fibre optics to distribute MC, SC, PM and Trigger signals





### **Global Orbit Feedback Architecture**





#### Real-time performance



- w Libera latency: 300  $\mu \textbf{s}$
- ${\color{black}{$\mathbf{s}$}}$  Gigabit Ethernet transmission time: 10  $\mu {\color{black}{$\mathbf{s}$}}$
- **u** Ethernet switch latency:  $1 \ \mu s$
- ${\color{black} {\color{black} \textbf{v}}}$  Reflective Memory Latency (BPMs and correctors data): 25  ${\color{black} \mu \textbf{s}}$
- **u** matrix multiplication and 14 control channels (LP Filter + PID + 10 HS): 21  $\mu$ s
- w DAC settings: 10  $\mu \textbf{s}$
- w all real-time tasks executed in 60-80  $\mu \textbf{s}$

CPU Load (G4 PowerPC @ 1.3 GHz)

- **u** feedback processing under RTAI: 60-70 %
- 8 TANGO servers (25 devices), control system interface, FFT of 10000 samples
  20 times per second with transmission to the client: 20%

#### Local Stations





One of the twelve local stations

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#### **Correction and Control Algorithms**



- SVD algorithm to invert the response matrix (48/24 eigenvalues)
- PID ( $K_P=3$ ,  $K_I=0.01$ ,  $K_D=5$ ,  $f_c=100Hz$ ), 3dB attenuation point at 150 Hz
- Harmonic Suppressors at: 50, 100, 150, 200, 250 and 300 Hz



#### Diagnostic Features

Diagnostic capabilities for machine physics studies, investigation of beam noise sources, searching of malfunctioning machine components

#### » Data recording:

Sech local station stores.

**and correctors**);

5 days of 1Hz data;

Master station stores.

**b** 5 seconds of 10kHz synchronous data of all BPMs and correctors

**Post Mortem Analysis:** buffers stop automatically under given conditions on BPM signals allowing beam dump detection

Arbitrary Waveform generation: driven by the master station, used to measure the corrector magnets transfer function







#### **Diagnostic Features**





# Spectrum of the beam position during a smooth loop closure



Post mortem data displayed in a 3-D plot: evolution of the horizontal closed orbit after interruption of the RF voltage in the accelerating cavities



Amplitude and phase response of a corrector magnet measured by exciting it with sinus waves at different frequencies



#### **Closed Loop Noise Attenuation**



Closed loop transfer function (sensitivity function) showing the attenuation of noise components as a function of frequency





Integrated amplitude spectrum of the beam position noise measured by a BPM with feedback off and on





Average BPM rms in  $\mu\text{m}$  in the 0-5 Hz and 0-200 Hz frequency range with feedback off/on

|        | 0 - 5 Hz   | 0 - 5 Hz | 0 - 200 Hz | 0 - 200 Hz |
|--------|------------|----------|------------|------------|
|        | Horizontal | Vertical | Horizontal | Vertical   |
| FB off | 0.4        | 0.15     | 3.5        | 2.1        |
| FB on  | 0.1        | 0.06     | 1.1        | 0.7        |



Horizontal beam position measured by a low-gap BPM with feedback off/on





Effect of the feedback in the vertical plane measured by an electron (top) and a photon (bottom) BPM. The beam orbit is perturbed by the operations of the electromagnetic elliptical wiggler



#### **Control Room Panels**



| - Global Feedback Status        | ]                                       |
|---------------------------------|---|
|                                 |   |
| ON                              |   |
| On                              |   |
| Standby Off                     | •                                       |
| - Max. Correctors' Strength [%] |   |
| H: 5.5 00 V. 00 10              | 0 40 70<br>70 80<br>77 90<br>77 90<br>6 |
| -BPMs rms (Average)             |   |
| H: 0.103 [um] V: 0.05           | i4 [um]                                 |
| - Difference Orbit rms          |   |
| H: 1.584 [um] V: 1.83           | 12 [um]                                 |
| View Expert Panel               |   |
| View Synoptic                   |   |
| View Orbit and Correctors       |   |

**Control Room Operator Panel** 

|                       | 1       | Loops          |  |
|-----------------------|---------|----------------|--|
| Dispersio             | n Loop  |                |  |
|                       | On      | Enable         |  |
|                       |         | Disable        |  |
| 499654000.0           |         | Starting RF    |  |
|                       | 0.0     | Required Diff. |  |
| 0                     | 0.0     | Applied Diff.  |  |
| 499654000.0           |         | Current RF     |  |
| 49965                 | 4000.0  | Current RF     |  |
| 49965<br>- Drift Loop |         | Current RF     |  |
|                       |         |                |  |
| 1                     | Off<br> | Enable         |  |
| - Drift Loop          | Off<br> | Enable         |  |

#### Expert Panel

#### **Control Room Panels**





#### Orbit Survey Panel

#### **Control Room Panels**





**Correctors Survey Panel** 

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#### Libera at Elettra



**u** 107 Libera Electron purchased in 2006, 100 installed

**u** Release 1.42 presently used, 1.60 received and partially tested in laboratory

Embedded Tango Device Server running in the SBC on top of the Generic Server (still not possible without it)

Sigabit Ethernet interface defined together with I-Tech works fine: straightforward commissioning, reliable operation, negligible jitter

After the first difficulties following the delivery (middle 2006) due to young software/firmware and a few hardware bugs, now Libera Electron is stable and with acceptable performance for Elettra

**a** A list of new features and improvements agreed with other Libera users have been delivered to I-Tech



An annoying problem still to be solved is the change in position readings when the attenuators are switched: steps ranging from 0 to 5  $\mu m$ 

Problem momentarily bypassed by disabling the ACG when the feedback is activated

