

Bardorfer Aleš

Libera LLRF Software

ales@i-tech.si



17 September 2009

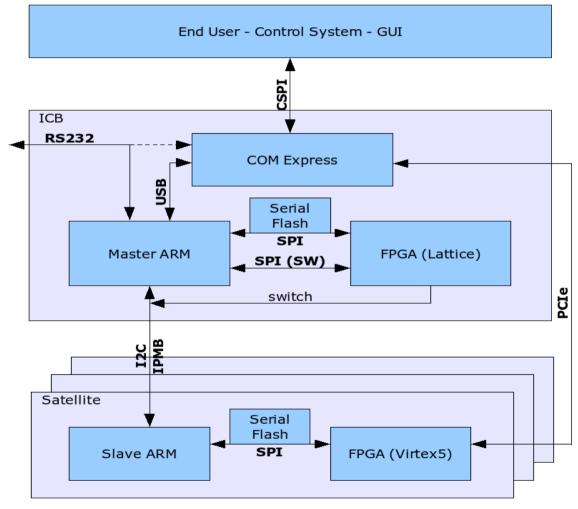
Libera LLRF SW Concept

- Generic as much as possible
- @ Low level:
 - 1-1 relation to HW satellite boards
 - Modular, but with minimal or no impact on performance
- @ Mid & High level:
 - Generic data paths
 - High level mapping for "instrument specifics"

Low level (Chasis) Software

- As close to IPMI standard as possible (Intelligent Platform Management Interface)
- Firmware upgrades
- JTAG access (FPGA debugging)
- Environmental monitoring
 - Temperature
 - Voltages
 - Fan speed

Low Level SW



Mid & High Level Software

GUI/CLI EPICS TANGO Generic Server (Instrument definitions) HL MCI LL MCI (Flat-top) LL MCI (DSP) LL MCI (SA) **HL** driver LL driver (ADC9) LL driver (VM) LL driver (TCM) LL driver (ICB) HW (ADC9) HW (VM) HW (TCM) HW (ICB)



Mid Level Software

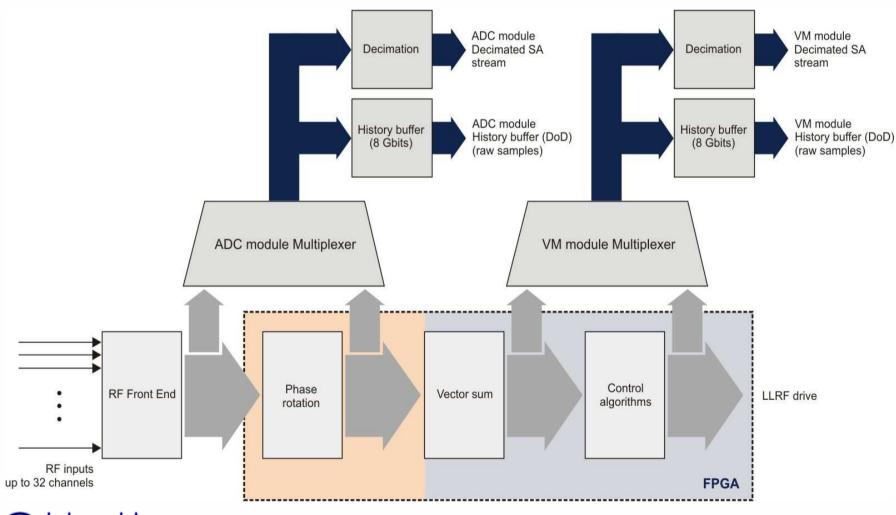
FPGA modules on internal bus:

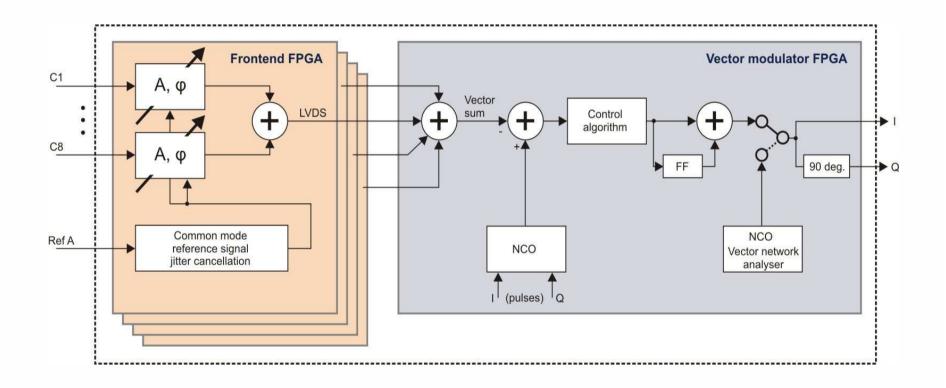
- ADC, DAC, I/O, DDR2, PCIe
- Timing & synchronization
- DSP & Application

GNU/Linux driver modules:

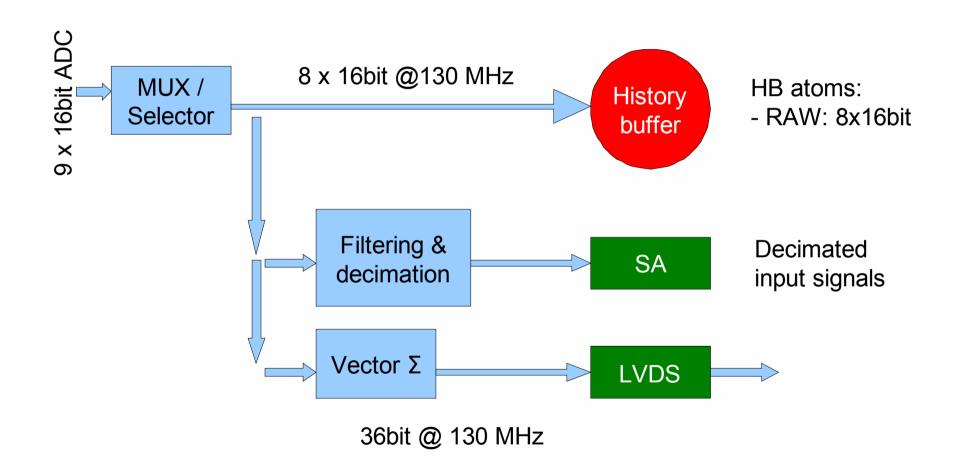
- Flat-top, SA, DSP channels
- DMA
- Built-in debugging

LLRF Application & Monitoring

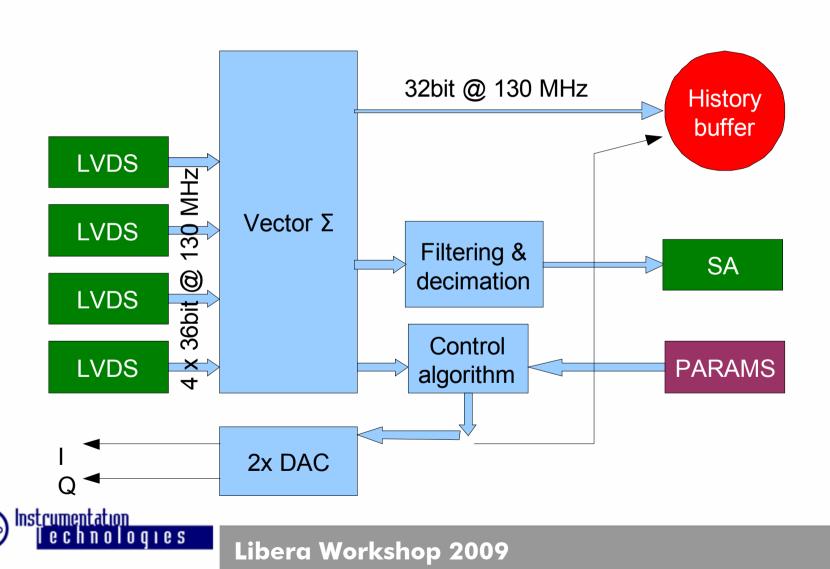




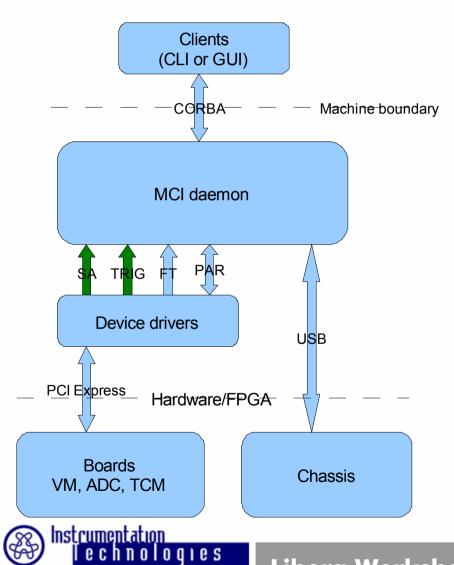
LLRF - Data Paths (ADC9)



LLRF - Data Paths (VM)



Software Interfaces



- Measurement Control Instrument (MCI) is implemented in MCI daemon:
- Enumeration: List of boards, signals, sensors.
- Information (attributes, state,...) about board, signal, sensor, application.
- Provide signal data via callback receiver: bounded to BoardID, SigID, stream type (SA, Flat-top) and stream processing (eRaw/eAmpPhase/eIQ).
- Provide sensors attributes and data via USB IPMI protocol.
- LLRF application specific control (Sweep, Decay, Stability, Loop control, Trigger, ...).
- Chassis control (status, temperature control, FPGA load, Power control, ...).

